Towards Parallel Learned Sorting

Ivan Carvalho Supervisor: Dr. Ramon Lawrence

- Performance of Sorting impacts many common operations
- Quicksort can sort an array in $\mathcal{O}(n \log n)$
 - The lower bound for comparison-based sorting is $\Omega(n \log n)$
- Quicksort is the default algorithm available in many languages/libaries (e.g. C++ STL)

Can we beat Quicksort and push the boundary of sorting performance?

Yes, we can beat Quicksort (albeit it's not easy).

In-Place Parallel Super Scalar Sample Sort (IPS⁴o)

- State-of-the-Art Sorting Algorithm
- Generalization of Quicksort: sorting with k pivots
- Implementation has many desirable properties

Desirable Properties of IPS⁴o

In-Place Partitioning

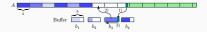


Figure 1: Example of in-place partitioning IPS⁴ o where each shade of blue represents elements assigned to a different bucket and green represents elements never visited. Instead of placing the elements directly to their position, IPS⁴ o places them into buffers and flushes the elements to the array when a buffer becomes full. After, defragmentation is executed to make the buckets contiguous. Reprinted from Axtmann et al., 2022.

- Branchless Decision Trees
 - Built from αk 1 samples (oversampling for k-pivot Quicksort)
 - Extremely efficient implementation of a decision tree

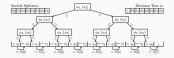


Figure 2: IPS⁴o organizes the pivots in a decison tree structure for quickly finding the correct bucket for an element. Reprinted from Axtmann et al., 2022.

- Parallelism
 - Custom task scheduler
 - Each task in IPS⁴o has a parallel implementation
- Reusable Framework
 - Code can be reused to implement variants of the algorithm
 - In-place Parallel Super Scalar Radix Sort (IPS²Ra)

Emerging field using machine learning to create highly efficient indexes that outperform traditional indexes (i.e. B-Trees)

Some indexes worth mentioning are:

- Recursive Model Index
- Piecewise Geometric Model Index
- RadixSpline
- Updatable Learned Index with Precise Positions

We will talk about ML-Enhanced Sorting. ML-Enhanced Sorting is intrinsically connected to Learned Indexes and reuses the models from Learned Indexes.

New paradigm: Machine Learning Enhanced Sorting Main idea: if there exists a model F that predicts the sorted position of a key x, we can sort the array in O(n) by moving each element to its correct location with A[F(x)] = x.

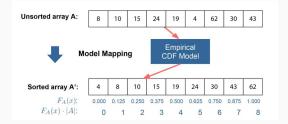


Figure 3: Ideal case of ML-enhanced with a perfect model. Reprinted from Kristo et al., 2020.

First challenge: F(x) is not given. However, ML can overcome that: we sample data and learn F(x).

But what kind of ML is useful to learn F(x)? One possible solution is to use Empirical Cumulative Distribute Functions (eCDF).

eCDF yields the probability $P(A \le x)$ that an element is smaller than x, hence for an array with N:

$$pos = F(x) = \lfloor N \cdot P(A \le x) \rfloor$$

There are more challenges even after we have F(x):

- **Inversions**: Pair of elements with a < b but F(a) > F(b)
- **Collisions**: Pair of elements with F(a) = F(b)
 - Collisions are exacerbated when there are many duplicates as it is guaranteed they will collide at F(x)

Learned Sort 2.0: practical implementation of ML-enhanced sorting with outstanding performance

- Uses the Recursive Model Index to model the eCDF
- Performs two rounds of partitioning using the model similarly to IPS⁴o
- Executes Insertion Sort to correct (very few) mistakes from the model

Limitations

- Cannot sort strings
- No parallel implementation is available

We are the first work to interpret $\mathsf{IPS}^4\mathsf{o}$ as a ML-enhanced algorithm, which has two consequences:

- First consequence is that models from the field of Learned Indexes can be used to create variants of IPS⁴o
- Second consequence is that IPS⁴ o provides a framework to efficiently parallelize ML-enhanced sorting algorithms

We introduce the In-Place Parallel Learned Sorting (IPLS) algorithm to prove our point. We use a model from Learned Indexes using the IPS⁴o framework to achieve parallel learned sorting.

Linear Models: partition based model.

Described by three parameters: the number of buckets k, the slope a and the constant term b

$$F(x) = \begin{cases} 0, & \text{if } \lfloor a \cdot x + b \rfloor < 0 \\ k - 1, & \text{if } \lfloor a \cdot x + b \rfloor \ge k \\ \lfloor a \cdot x + b \rfloor, & \text{otherwise} \end{cases}$$

Consequence of Linear Models: $x_i < x_j \rightarrow F(x_i) \leq F(x_j)$

How do we train a linear model for sorting?

Idea: minimize the maximum number of elements in a bucket.

Fastest Minimum Conflict Degree (FMCD):

- Model used by the Updatable Learned Index with Precise Positions
- Trains in $\mathcal{O}(S)$ for S samples
- Guarantees at most S/3 elements will be in the same partition
 - Reasonable to assume at most N/3 elements will be in the same bucket for the whole array as well
 - N/3 bound yields that on average O(log N) recursive partition steps will be performed no matter what input is given

In-Place Parallel Learned Sorting (IPLS)

IPLS extends IPS^4 o and has the goal to show that the framework can be used to implement a parallel version of ML-enhanced sorting:

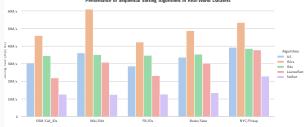
- IPLS partitions the data in k = 256 buckets using linear models. It samples $\alpha k 1$ random elements from the array with $\alpha = 0.2 \log N$.
- Then, it trains a linear model on the samples using the FMCD algorithm discussed earlier. The linear model F(x) is then used to predict the bucket for each element.
- For n ≤ 2¹², IPLS uses SkaSort as the base case (fast RadixSort)

We compare the performance IPLS to other sorting algorithms on a **m5zn.metal** instance from AWS. The instance runs a Intel® Xeon® Platinum 8252C CPU @ 3.80GHz with 48 cores and 192 GB of RAM. The algorithms we compare against are:

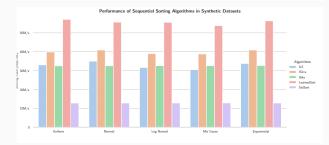
- IPS⁴o
- IPS²Ra
- Learned Sort
- std::sort

We compare both sequential and parallel settings. For the sequential case, we refer to the algorithms as IS^4 o, IS^2Ra and ILS.

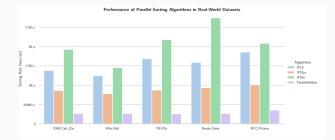
Results (Sequential)

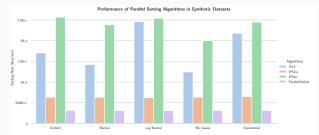


Performance of Sequential Sorting Algorithms in Real-World Datasets



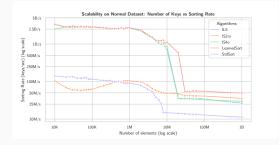
Results (Parallel)

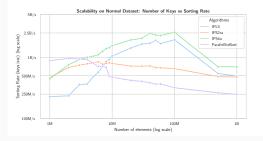




16

Results (Scalability)





Analysis of Results

Sequential

- Learned Sort dominates on synthetic data and IS²Ra dominates on real-world data
- ILS is competitive with IS⁴o and wins in some datasets
- Scalability of ILS and IS⁴o is almost identical

Parallel

- IPS⁴o dominates on all datasets
- IPLS comes second and IPS²Ra comes third
- Can interpret the results as which algorithms creates more independent subproblems
- Scalability preservers the same relative ordering for the algorithms, but the overhead of multithreading makes the parllel version slower than serial version for $n < 10^6$

- 1. IPS⁴o provides a framework to implement parallel ML-enhanced sorting
- 2. We achieved parallel ML-enhanced sorting with linear models trained with FMCD
- 3. Advances in the field of Learned Indexes can also benefit sorting
 - Future models will benefit both applications and could potentially dethrone IPS⁴o

Appendix

 $\mathsf{Sample}\ \mathsf{Data} \to \mathsf{Sort}\ \mathsf{Sample} \to \mathsf{Train}\ \mathsf{Model} \to \mathsf{Predict}\ \mathsf{on}\ \mathsf{Keys}$

Computing Budget: cost of executing all four phases from ML-enhanced sorting must be less than or equal to the the cost of executing Quicksort

CDF Based Models:

- Output is in [0,1)
- Goal is to minimize the error of the CDF predictions
 - Mean-Squared Error is a common metric

Partition Based Models:

- Output is in $\{0, 1, 2, \dots, k-1\}$
- Goal is related to minimizing either:
 - Average number of elements
 - Maximum number of elements

Recursive Model Index (RMI): eCDF based model.

A RMI has *L* levels, and each level *i* has M_i models that recursively select the model in the next level of the RMI. The output F(x) of an RMI is a value in [0, 1) that is an approximation for $P(A \le x)$.

$$f_i(x) = f_i^{(\lfloor M_i f_{i-1}(x) \rfloor)}(x)$$

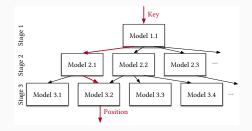


Figure 4: Generic RMI with multiple levels.

RMIs in practice are much simpler. They are limited to L = 2 levels, hence Learned Sort uses an RMI that is closer to:

$$F(x) = f_2^{(\lfloor M_2 f_1^{(1)}(x) \rfloor)}(x)$$

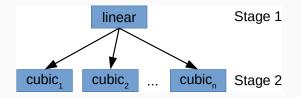


Figure 5: RMI used in practice with two levels.

Decision Trees: partition based model.

Predicts the partition bucket \mathcal{B}_i for each x_i with the property that if $x_i < x_j$, then $\mathcal{B}_i \leq \mathcal{B}_j$. Used by IPS⁴o.

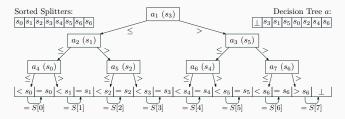


Figure 6: IPS⁴o organizes the pivots in a decison tree structure for quickly finding the correct bucket for an element.