

Last Time:

Continuity Eq'n: $\vec{\nabla} \cdot \vec{J} = -\frac{dp}{dt}$

For steady currents, $\frac{dp}{dt} = 0 \Rightarrow$

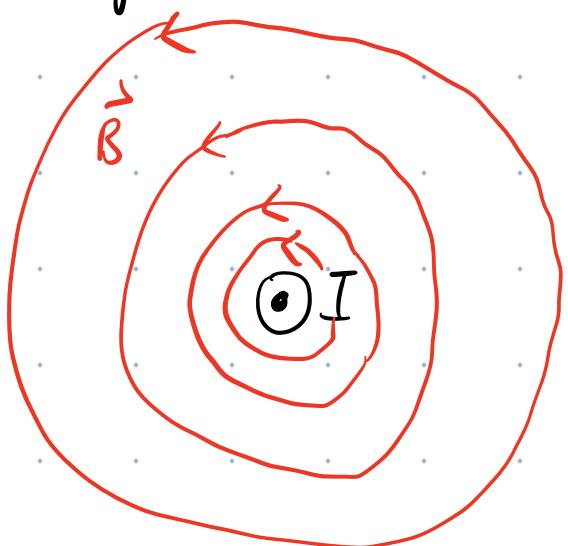
$$\boxed{\vec{\nabla} \cdot \vec{J} = 0}$$

Biot-Savart Law:

$$\vec{B}(r) = \frac{\mu_0}{4\pi} \int \frac{\vec{I} \times \hat{r}}{r^2} dl'$$

Magnetic field due to a long, straight current:

$$\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{z}$$

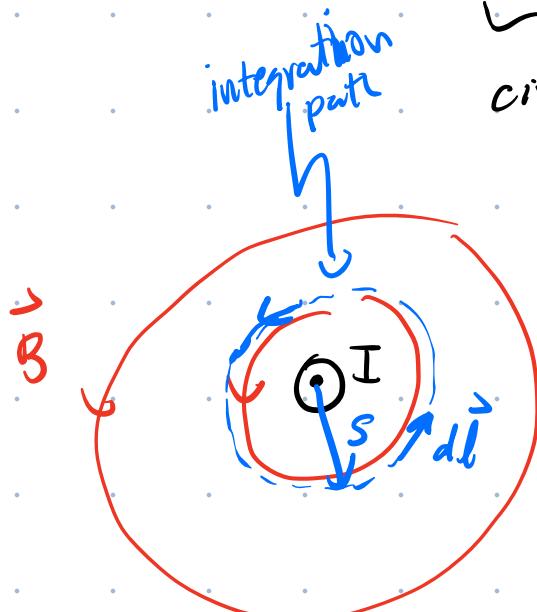


Today: Griffiths 5.3 The Divergence & Curr of \vec{B}

Let's try evaluating $\oint \vec{B} \cdot d\vec{l} = \int \vec{\nabla} \times \vec{B} \cdot da$

$\underbrace{}$ S Stoke's Th.

circulation



Select an integration path that matches the symmetry of \vec{B} .

$$\therefore d\vec{l} = dl \hat{z} \quad \vec{B} = \frac{\mu_0 I}{2\pi s} \hat{z}$$

$$\therefore \vec{B} \cdot d\vec{l} = \frac{\mu_0 I}{2\pi s} dl$$

$\underbrace{\phantom{\frac{\mu_0 I}{2\pi s}}}_{\text{const. on}}$
chosen integration path.

$$\oint \vec{B} \cdot d\vec{l} = \oint \frac{\mu_0 I}{2\pi s} dl = \frac{\mu_0 I}{2\pi s} \oint dl$$

$\underbrace{}_{\text{circumference of integration path}}$

Integral form of Ampère's Law.

apply stokes
Law

$$\therefore \oint \vec{B} \cdot d\vec{l} = \mu_0 I$$

$$= 2\pi S$$

So far, we've shown that this result is true for a long straight current. We want generalize for \vec{B} due to any steady current dist'n.

Note that, last time we showed

$$\int_S \vec{J} \cdot d\vec{a} = I$$

$$\int_S \vec{\nabla} \times \vec{B} \cdot d\vec{a} = \int_S (\mu_0 \vec{J}) \cdot d\vec{a}$$

must be equal

$$\therefore \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

differential form of Ampère's Law.

#

The goal is to reproduce # starting from the general Biot-Savart Law:

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times \hat{\vec{r}}}{r'^2} d\tau'$$

Integrate over primed coords which locate the source currents w.r.t. the origin. Want to find $\vec{\nabla} \times \vec{B}$ & $\vec{\nabla} \cdot \vec{B}$. The $\vec{\nabla}$ operator takes deriv. w.r.t. unprimed coords. which locate the field pt.

Start w/ $\vec{\nabla} \cdot \vec{B} = \vec{\nabla} \cdot \left(\frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times \hat{\vec{r}}}{r'^2} d\tau' \right)$

$$= \frac{\mu_0}{4\pi} \int \vec{\nabla} \cdot \left(\vec{J}(\vec{r}') \times \left(\frac{\hat{\vec{r}}}{r'^2} \right) \right) d\tau'$$

Apply product rule (6)
from Griffith's cover

$$\frac{\hat{r}}{r^2} \cdot (\vec{\nabla} \times \vec{J}(r')) - \vec{J}(r') \cdot \left(\vec{\nabla} \times \frac{\hat{r}}{r^2} \right)$$

since dev. w.r.t.
unprimed coords



$$\text{since } \frac{\hat{r}}{r^2} = \frac{\vec{r}}{r^3}$$

has no θ or ϕ dependence
and no θ or ϕ component
in spherical coords.

$$\therefore \vec{\nabla} \cdot \vec{B} = 0$$

True $\forall \vec{B}$ due to
steady currents.

Next, consider $\vec{\nabla} \times \vec{B} :$

$$\vec{\nabla} \times \vec{B} = \frac{\mu_0}{4\pi} \int \vec{\nabla} \times \left(\vec{J}(\vec{r}') \times \frac{\hat{\vec{r}}}{r'^2} \right) d\tau'$$

Product rule
(8)

$$\left(\frac{\hat{\vec{r}}}{r'^2} \cdot \vec{\nabla} \right) \vec{J}(\vec{r}') - \left(\vec{J}(\vec{r}') \cdot \vec{\nabla} \right) \frac{\hat{\vec{r}}}{r'^2}$$

$$+ \vec{J}(\vec{r}') \left(\vec{\nabla} \cdot \frac{\hat{\vec{r}}}{r'^2} \right) - \frac{\hat{\vec{r}}}{r'^2} \left(\vec{\nabla} \cdot \vec{J}(\vec{r}') \right)$$

$\underbrace{\qquad\qquad}_{4\pi \delta^3(\vec{r})}$

$$\vec{\nabla} \times \vec{B} = \mu_0 \int \vec{J}(\vec{r}') \delta^3(\vec{r} - \vec{r}') d\tau'$$

$\overbrace{\vec{J}(\vec{r})}$

$$- \frac{\mu_0}{4\pi} \int \left(\vec{J}(\vec{r}') \cdot \vec{\nabla} \right) \frac{\hat{\vec{r}}}{r'^2} d\tau'$$

$\overbrace{\qquad\qquad\qquad}_{\text{Int}_2}$

selects
value of \vec{r}'
s.t. $\vec{r} - \vec{r}' = 0$

$$\Rightarrow \vec{r} = \vec{r}'$$

We will show that $\text{Int}_2 = 0$ s.t.

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

Aside: Consider $\frac{\partial}{\partial x} f(u)$ where $u = x - x'$

$$= \frac{df}{du} \frac{du}{dx}^1 = \frac{df}{du}$$

Consider $\frac{\partial}{\partial x'} f(u)$

$$= \frac{df}{du} \frac{du}{dx'}^{-1} = - \frac{df}{du}$$

$$\boxed{\frac{\partial}{\partial x'} f(u) = - \frac{\partial}{\partial x} f(u)}$$

By the same logic, $\vec{\nabla} \frac{\hat{R}}{R^2}$ in Int_2

is equiv. to $- \vec{\nabla}' \frac{\hat{R}}{R^2}$

$\therefore \text{Int}_2$ becomes:

$$-\frac{\mu_0}{4\pi} \int \left(\vec{J}(\vec{r}') \cdot \vec{\nabla}' \right) \frac{\hat{R}}{R^2} d\tau'$$

Consider just the x-comp. of $\frac{\hat{R}}{R^2}$ is Cartesian
coord.

$$\frac{\hat{R}}{R^2} = \frac{\vec{R}}{R^3}$$

$$\left(\vec{J}(\vec{r}') \cdot \vec{\nabla}' \right) \left(\frac{x - x'}{R^3} \right)$$

Product rule (5)

$$= \vec{\nabla}' \cdot \left(\frac{x - x'}{R^3} \vec{J}(\vec{r}') \right)$$

$$- \left(\frac{x - x'}{R^3} \right) \vec{\nabla}' \cdot \vec{J}(\vec{r}')$$

0 for steady currents

(continuity eq'n w/
 $\frac{\partial \phi}{\partial t} = 0$)

\therefore the x -component's contribution to Int_2 is:

$$\int_V \vec{\nabla} \cdot \left(\frac{x - x'}{\sqrt{r^3}} \vec{J}(\vec{r}') \right) d\tau'$$

Apply the divergence theorem

$$= \oint_S \frac{x - x'}{\sqrt{r^3}} \vec{J}(\vec{r}') \cdot d\vec{a}'$$

$S \leftarrow$ surface bounding the integral in Biot-Savart law that contains $\vec{J}(\vec{r}')$.

Choose surface to be large enough that $\vec{J}(\vec{r}') = 0$ everywhere on the surface s.t.

$\text{Int}_2 = 0$. (similar for $y \& z$ components).

Summary

Ampère's Law
in differential
form

$$\boxed{\vec{\nabla} \cdot \vec{B} = 0}$$
$$\rightarrow \boxed{\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}}$$

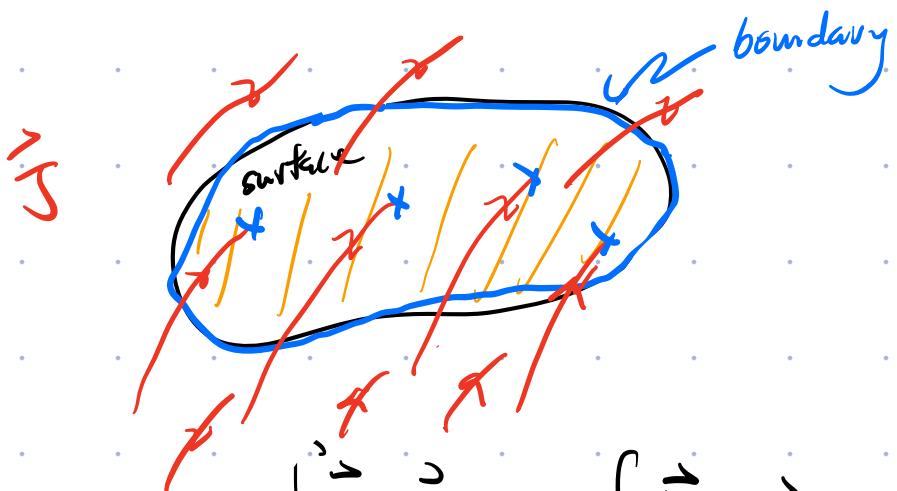
valid & magneto-statics.

5.3.3 Ampère's Law

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

Integrate

$$\int_S \vec{\nabla} \times \vec{B} \cdot d\vec{a} = \oint_{\text{boundary}} \vec{B} \cdot d\vec{l}$$

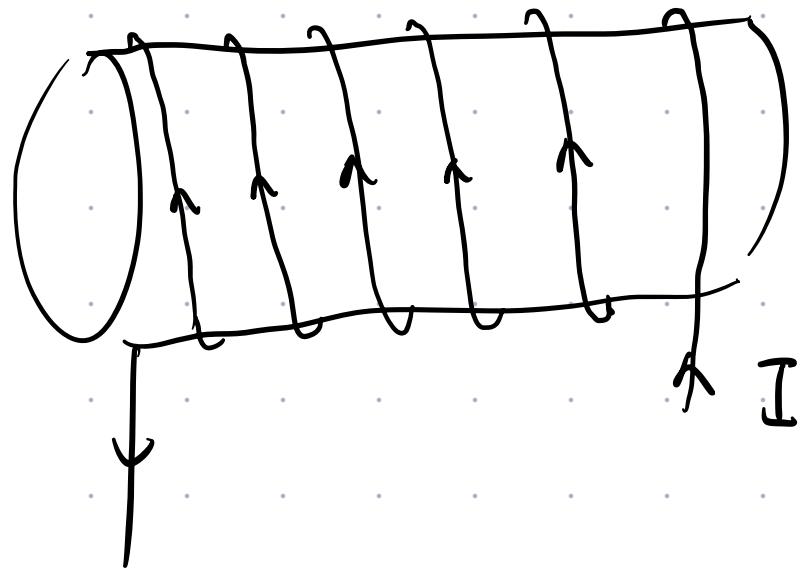


$$\oint_{\text{boundary}} \vec{B} \cdot d\vec{l} = \mu_0 \int_S \vec{J} \cdot d\vec{a} = \mu_0 I_{\text{end}}$$

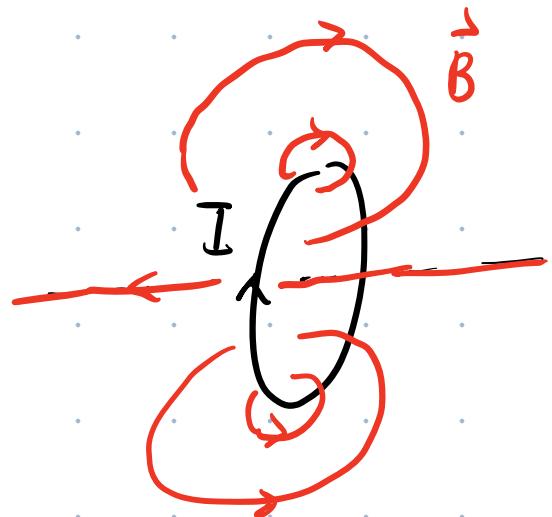
I_{end} \hookrightarrow total current passing surface S.

$\therefore \oint_{\text{boundary}} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{end}}$ integral form of Ampère's Law

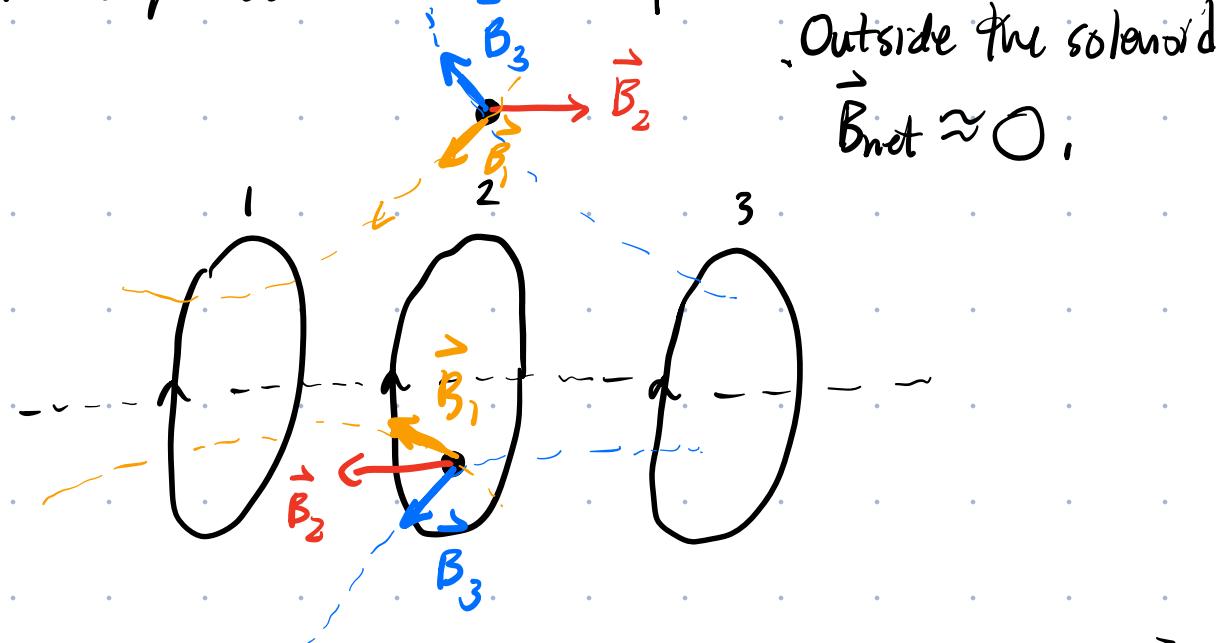
Eg. Find \vec{B} due to a long solenoid.



Like a series of current loops.



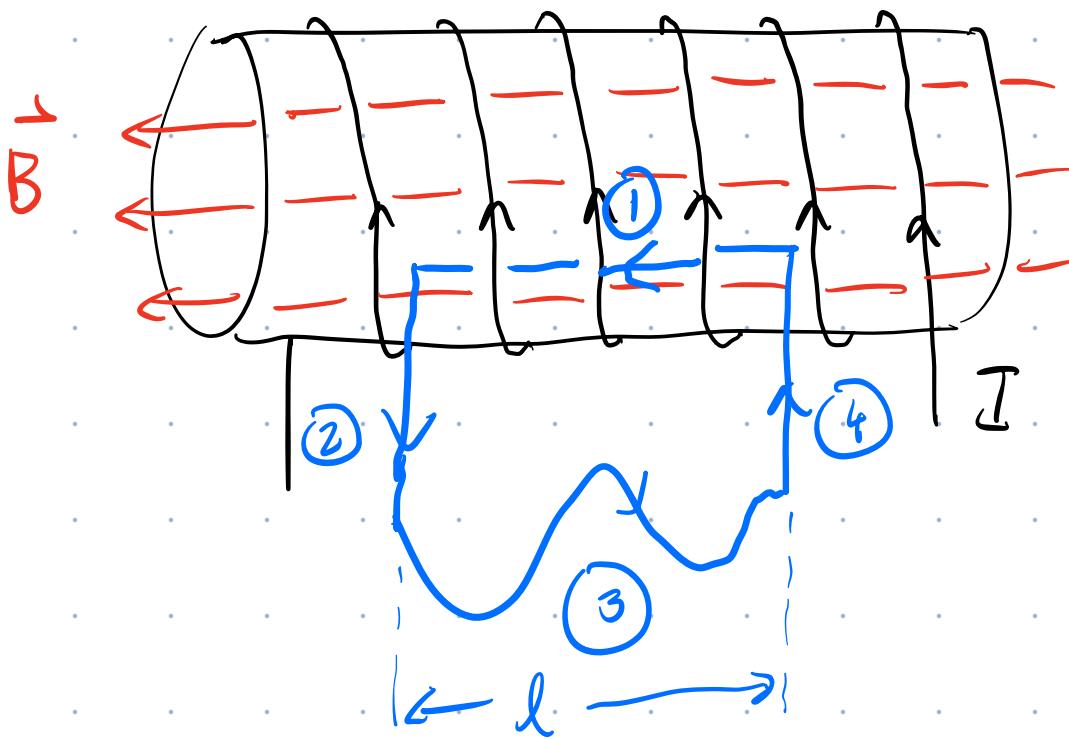
Consider a sequence of current loops



Inside solenoid, horizontal \vec{B} -field
is strong while the vertical component
vanishes

Apply Ampère's to the solenoid

$$\mathbf{B} = 0$$



1. Select an Ampérian loop/integration path

path: - should be \parallel or \perp to \vec{B}

- B should be const. when path \parallel to \vec{B} .

2. Find I_{end} (how much current passes through Ampérian loop)

N loops of the solenoid coil pass through the loop.

$$\therefore I_{\text{end}} = NI$$

3. Evaluate $\oint \vec{B} \cdot d\vec{l} = \int \vec{B} \cdot d\vec{l} + \int \vec{B} \cdot d\vec{l}$

(1)

(2)

$$+ \int \vec{B} \cdot d\vec{l} + \int \vec{B} \cdot d\vec{l}$$

(3)

(4)

$\vec{B} = 0$ b/c

$\vec{B} = 0$ for same reasons as (2)

$\vec{B} = 0$ everywhere on (3)

$\vec{B} \perp d\vec{l}$ inside
solenoid $\{ \vec{B} = 0$
outside solenoid

$$\oint \vec{B} \cdot d\vec{l} = \int \vec{B} \cdot d\vec{l} = \int B dl$$

(1)

since $\vec{B} \parallel d\vec{l}$ for (1)

$$= B \int dl$$

since (1) is same position
inside solenoid (same dist.
for solenoid axis)

$$= B l$$

l length of path (1)

Finally: $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{end}$

By

$$Bl = \mu_0 N I$$

n : no. of turns
per unit length.

$$\therefore B = \mu_0 \left(\frac{N}{l} \right) I$$

$$\therefore B = \mu_0 n I$$

\vec{B} inside solenoid is uniform.