

Griffiths Ch. 3: Laplace's Eq'n.Recall Poisson's Eq'n $\nabla^2 V = -\rho/\epsilon_0$ In a region where $\rho = 0$, this reduces to

Laplace's Eq'n

$$\nabla^2 V = 0$$

In Cartesian coords.

$$\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0 \quad \text{Partial diff. eq'n.}$$

3.1.2. Laplace's Eq'n in 1-D.

Strategy is to first work out some properties of the sol'n's to Laplace's eq'n in 1-D and then generalize to higher dimensions.

In 1-D

$$\frac{d^2V}{dx^2} = 0$$

$$\therefore \frac{dV}{dx} = m \quad (\text{a const.})$$

$$\Rightarrow V = mx + b \quad (\text{straight line})$$

The two integration const. are determined by boundary conditions.

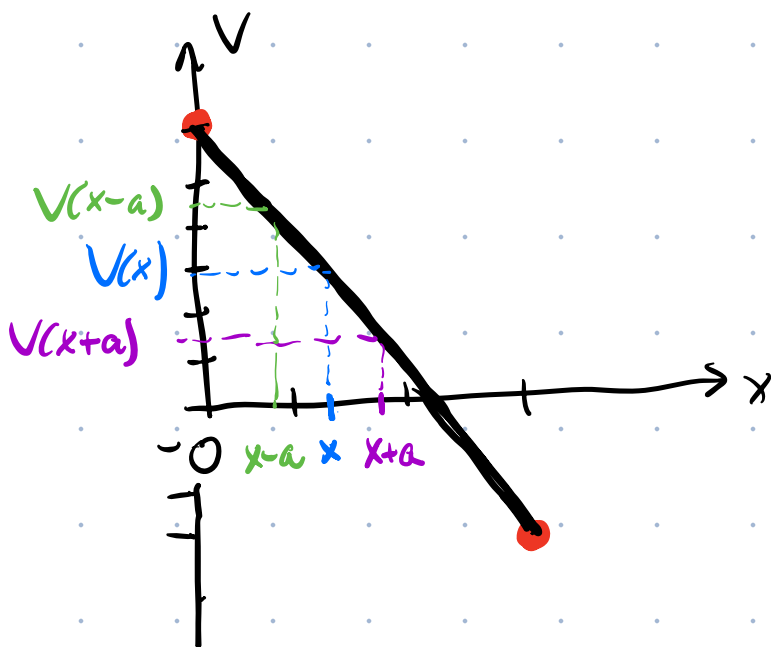
For example if $V(0) = 6$ & $V(3) = -3$

$$V(0) = m(0) + b = 6 \Rightarrow \underline{\underline{b = 6}}$$

$$V = mx + 6$$

$$V(3) = 3m + 6 = -3 \Rightarrow m = -3$$

$$V = -3x + 6$$



Note ①: $V(x)$ has no local minima or maxima.
 All extrema occur at the boundaries
 $(x=0, x=3)$

$$\frac{dV}{dx} = m \neq 0 \Rightarrow \text{no local min or max pts.}$$

$$\frac{d^2V}{dx^2} = 0 \quad \text{require } \frac{d^2V}{dx^2} < 0 \text{ for maxima}$$

$$\frac{d^2V}{dx^2} > 0 \text{ for minima.}$$

Note ②: $V(x)$ is the average of $V(x+a)$ and $V(x-a)$ for any a .

3.1.3 Laplace's Eq'n in 2-D

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} = 0$$

Aside: Finding extrema of multivariable fns

I'll write down procedure for finding local minima & maxima for 2-D fns.

1. If $f(x, y)$, find all (x, y) pts that satisfy

$$\frac{\partial f}{\partial x} = 0 \quad \frac{\partial f}{\partial y} = 0$$

2. Find the Hessian matrix

$$H = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

3. For each pt. (x, y) from ①, get a minimum or maximum if $\det(H) > 0$.

$$\det(H) = \left(\frac{\partial^2 f}{\partial x^2} \right) \left(\frac{\partial^2 f}{\partial y^2} \right) - \left(\frac{\partial^2 f}{\partial x \partial y} \right)^2$$

\therefore can only get minima or maxima if

$$\frac{\partial^2 f}{\partial x^2} \text{ \& \ } \frac{\partial^2 f}{\partial y^2} \text{ have the same sign!}$$

$\left(\begin{array}{l} \text{If } \det(H) < 0, \text{ saddle pt.} \\ \text{If } \det(H) = 0, \text{ test inconclusive} \end{array} \right)$

$$\nabla^2 f = 0 = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

$\therefore \frac{\partial^2 f}{\partial x^2} \text{ \& \ } \frac{\partial^2 f}{\partial y^2} \text{ must have opp. sign.}$

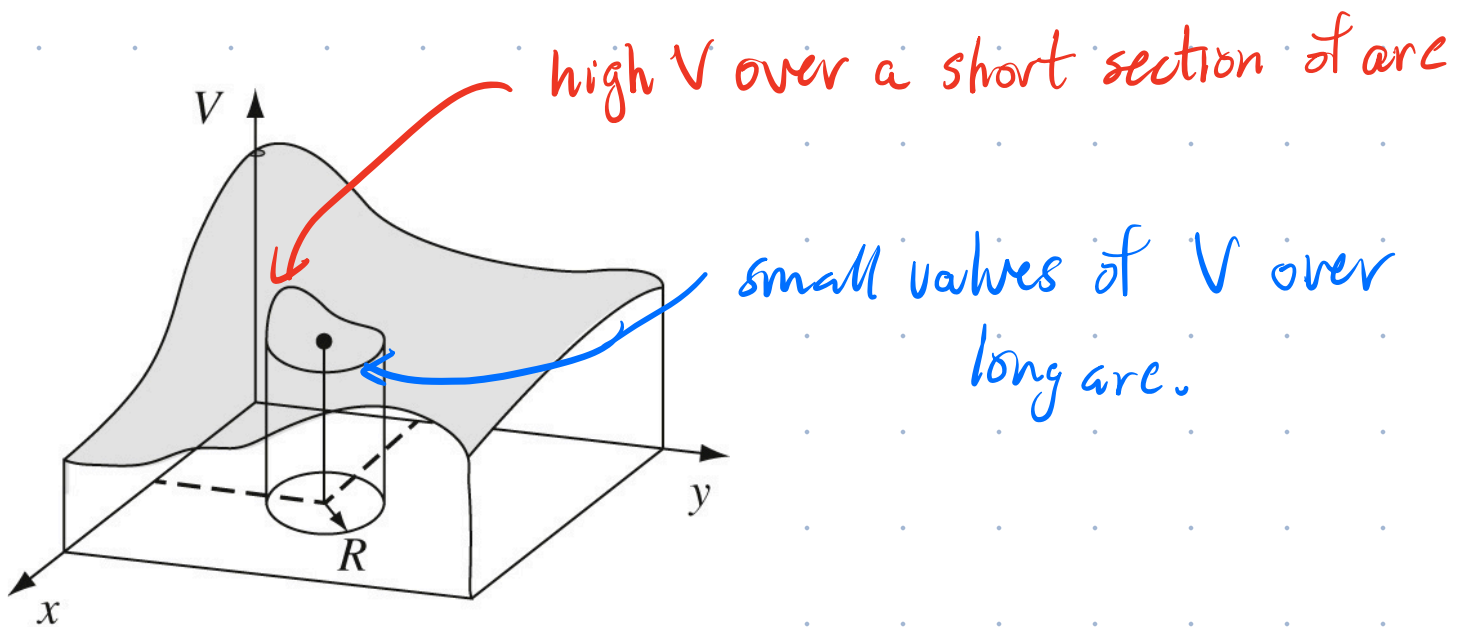
$\therefore f$ cannot have local extrema.

This argument generalizes to 3-D

Note ①

\Rightarrow In 1, 2, or 3-D sol'n's to Laplace's eq'n contain no extrema except at boundaries

In 2-D can picture sol'n's to Laplace's eq'n by consider a wavy line cut around perimeter of a box. Then stretch rubber membrane over box. The shape of membrane gives sol'n's to Laplace's eq'n's (called Harmonic fun).



Note ② If you draw a circle of radius R around the pt. (x, y) , the average of V around the circle is equal to V at pt. (x, y) .

$$\frac{1}{2\pi R} \oint V(x, y) d\ell$$

circle of
radius R

i.e. $V(x, y)$ is equal to average of V around circumference of circle.

3.1.4 Laplace's eq'n in 3-D

Note ①: $V(x, y, z)$ sol'ns have no extrema.

Note ②: Value of V at (x, y, z) is equal to average of V over a sphere of radius R with pt. (x, y, z) @ centre of sphere.

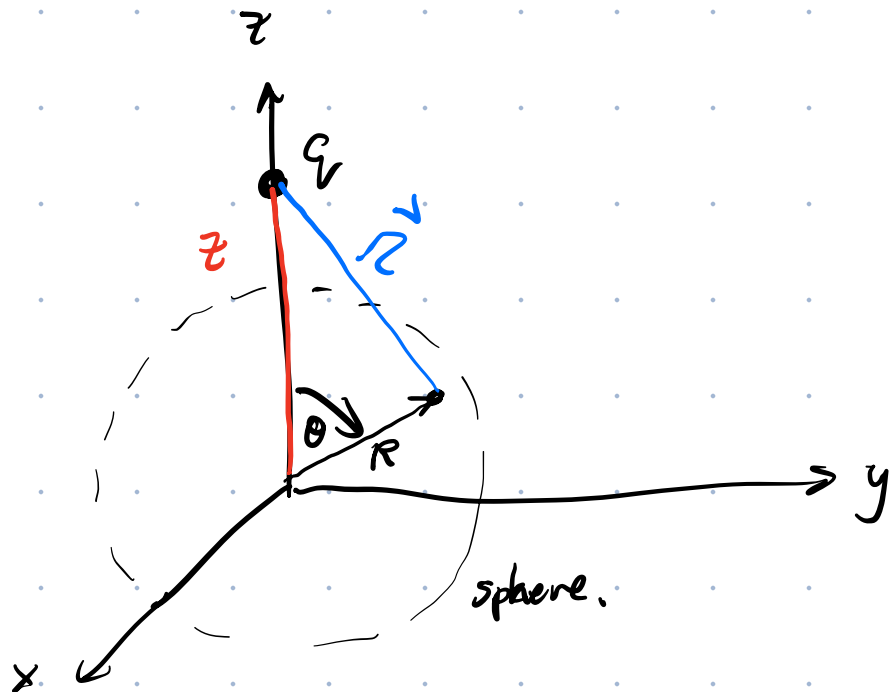
$$V(x, y, z) = \frac{1}{4\pi R^2} \int V da$$

Sphere of radius R

Proof of ②

Consider a pt. charge q on z axis. Find V at $(x, y, z) = (0, 0, 0)$.

Expect $V = \frac{1}{4\pi\epsilon_0} \frac{q}{z}$

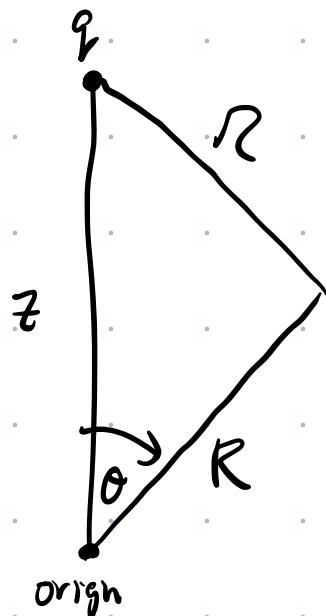


Inside sphere $\rho = 0 \therefore \nabla^2 V = 0$

Know $V = \frac{1}{4\pi\epsilon_0} \frac{q}{R}$

Law of cosines

$$R^2 = z^2 + R^2 - 2zR \cos \theta$$



$$V_{\text{sphere}} = \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{z^2 + R^2 - 2zR \cos \theta}}$$

$$V = \frac{1}{4\pi R^2} \frac{q}{4\pi\epsilon_0} \int \frac{1}{\sqrt{z^2 + R^2 - 2zR \cos \theta}} R^2 \sin \theta d\theta d\phi$$

$$= \frac{1}{2} \frac{q}{4\pi\epsilon_0} \int_{\theta=0}^{\pi} \frac{\sin \theta d\theta}{\sqrt{z^2 + R^2 - 2zR \cos \theta}}$$

$$u = z^2 + R^2 - 2zR \cos \theta$$

$$du = 2zR \sin \theta d\theta \therefore \sin \theta d\theta = \frac{du}{2zR}$$

$$\text{when } \theta = 0, \quad u = z^2 + R^2 - 2zR = (z-R)^2$$

$$\theta = \pi \quad u = z^2 + R^2 + 2zR = (z+R)^2$$

$$\frac{1}{4zR} \frac{q}{4\pi\epsilon_0} \int_{u=(z-R)^2}^{(z+R)^2} u^{-1/2} du$$

$$= \frac{1}{2zR} \frac{q}{4\pi\epsilon_0} u^{1/2} \Big|_{(z-R)^2}^{(z+R)^2} = \frac{1}{2zR} \frac{q}{4\pi\epsilon_0} \left[\cancel{(z+R)} - \cancel{(z-R)} \right]$$

$$= \frac{q}{4\pi\epsilon_0 z}$$

✓
Pt. charge
a dist. z
away. ✓

We can treat any dist'n of charge as a collection of pt. charges that obey the superposition principle. \therefore This proof generalizes to any ρ .

3.1.5 Uniqueness Theorems

First Uniqueness Theorem: The sol'n to $\nabla^2 V = 0$ in a volume V is uniquely determined if V is specified on the boundary of surrounding surface S .

Proof: Suppose there are two sol'ns, s.t.

$$\nabla^2 V_1 = 0 \quad \& \quad \nabla^2 V_2 = 0$$

with both V_1 & V_2 satisfying boundary conditions.

Consider $V_3 = V_1 - V_2$ } implies V_3 is zero everywhere on the boundary.

$$\nabla^2 V_3 = \nabla^2 (V_1 - V_2) = \underbrace{\nabla^2 V_1}_0 - \underbrace{\nabla^2 V_2}_0 = 0$$

$\therefore V_3$ satisfies Laplace's eq'n.

Since V_3 has min & max values of zero at boundary, property ① requires that $V_3 = 0$ everywhere.

$$V_3 = V_1 - V_2 = 0 \Rightarrow \boxed{V_1 = V_2}$$

If $\rho \neq 0$ in volume V :

$$\nabla^2 V_1 = -\rho/\epsilon_0 \quad \nabla^2 V_2 = -\rho/\epsilon_0$$

$$\therefore \text{If } V_3 = V_1 - V_2$$

$$\nabla^2 V_3 = \nabla^2 V_1 - \nabla^2 V_2 = 0$$

⋮

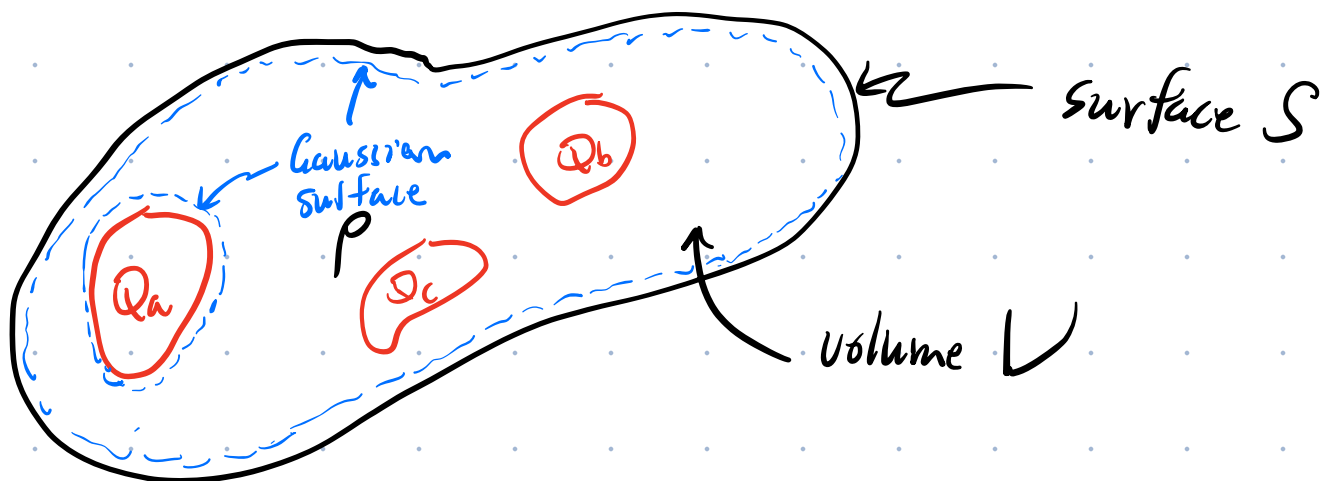
again find $V_1 = V_2$.

Corollary to first uniqueness theorem:

The potential V in volume V is uniquely determined if charge density ρ in V and the value of V on all boundaries are specified.

3.1.6 Conductors & 2nd Uniqueness Theorem:

Region of space V bounded by a surface S .



Inside the volume:

- ρ is known
- there are conductors (red) w/ charge Q_i on their surface.

The volume V is either unbounded (i.e. infinite) or surrounded by a conducting surface S .

\Rightarrow In either case, V is constant on bounding surface.

Second Uniqueness Theorem.

In a volume V containing conductors and a specified charge density ρ , \vec{E} is uniquely determined if the total charge on each conductor is given.

Proof: Suppose \vec{E}_1 & \vec{E}_2 are possible.

In between conductors, each \vec{E} must satisfy Gauss's law in differential form:

$$\vec{\nabla} \cdot \vec{E}_1 = \rho / \epsilon_0$$

$$\vec{\nabla} \cdot \vec{E}_2 = \rho / \epsilon_0$$

They also must satisfy integral form around each conductor.

$$\oint_{\text{conductor } i} \vec{E}_1 \cdot d\vec{a} = \frac{Q_i}{\epsilon_0}$$

$$\oint \vec{E}_2 \cdot d\vec{a} = \frac{Q_i}{\epsilon_0}$$

For a Gaussian surface just inside surrounding boundary

$$\oint_{\text{outer}} \vec{E}_1 \cdot d\vec{a} = \frac{Q_{\text{tot}}}{\epsilon_0}$$

$$\oint_{\text{outer}} \vec{E}_2 \cdot d\vec{a} = \frac{Q_{\text{tot}}}{\epsilon_0}$$

Like before, examine $\vec{E}_3 = \vec{E}_1 - \vec{E}_2$

$$\therefore \vec{\nabla} \cdot \vec{E}_3 = 0$$

$$\oint \vec{E}_3 \cdot d\vec{a} = 0 \quad \forall \text{ boundaries} \quad *$$

Next consider.

$$\vec{\nabla} \cdot (V_3 \vec{E}_3) = V_3 (\underbrace{\vec{\nabla} \cdot \vec{E}_3}_0) + \vec{E}_3 \cdot (\underbrace{\vec{\nabla} V_3}_{-\vec{E}_3})$$

Product Rule (5)

$$\vec{\nabla} \cdot (V_3 \vec{E}_3) = -E_3^2$$

$$\therefore \int_V \vec{\nabla} \cdot (V_3 \vec{E}_3) d\tau = - \int_V E_3^2 d\tau$$

\Downarrow divergence Theorem

$$\therefore \oint_{\text{all surfaces}} V_3 \vec{E}_3 \cdot d\vec{a} = - \int_V E_3^2 d\tau$$

All surfaces are next to conductors where V is const. $\therefore V_3 = \text{const.}$

$$V_3 \oint \vec{E}_3 \cdot d\vec{\omega} = - \int_V E_3^2 d\tau \Rightarrow E_3 = 0.$$

$= 0$
by $\textcircled{\neq}$

but since $\vec{E}_3 = \vec{E}_1 - \vec{E}_2 = 0$

$$\Rightarrow \vec{E}_1 = \vec{E}_2$$