

- Assignment #5 due today
 - Start working on your formal report
 - ▣ due April 7 @ 14:00 in SCI 241
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Last time: Used the method of maximum likelihood to develop a technique to fit data $(x_i, y_i \pm \sigma_i)$ to a function of the form:

$$y(x) = a_1 f_1(x) + a_2 f_2(x) + \dots + a_m f_m(x)$$

$$= \sum_{k=1}^m a_k f_k(x)$$

Found that $\underline{a} = \underline{\Sigma \beta} = \underline{\alpha^{-1} \beta}$

where

$$\beta_k = \left| \sum_{i=1}^N \frac{1}{\sigma_i^2} y_i f_k(x_i) \right| \quad \alpha_{lk} = \left[\sum_{i=1}^N \left[\frac{1}{\sigma_i^2} f_l(x_i) f_k(x_i) \right] \right]$$

$a_k = \alpha_k$

Today: Apply prop. of errors to $a_k(y_1, y_2, \dots, y_n)$
in order to find σ_k .

Will show that the diagonal elements of Σ
give the square of the uncertainty. Specifically,

$$\Sigma_{kk} = \chi_{kk}^{-1} = \sigma_k^2$$

Apply prop. of errors to $a_k(y_1, y_2, \dots, y_n)$

$$\begin{aligned}\sigma_k^2 &= \left(\frac{\partial a_k}{\partial y_1} \sigma_1 \right)^2 + \left(\frac{\partial a_k}{\partial y_2} \sigma_2 \right)^2 + \dots + \left(\frac{\partial a_k}{\partial y_n} \sigma_n \right)^2 \\ &= \sum_{j=1}^n \left(\frac{\partial a_k}{\partial y_j} \sigma_j \right)^2\end{aligned}$$

If $m=3$, then symmetric depend on y_i

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \underbrace{\begin{pmatrix} \Sigma_{11} & \Sigma_{12} & \Sigma_{13} \\ \Sigma_{12} & \Sigma_{22} & \Sigma_{23} \\ \Sigma_{13} & \Sigma_{23} & \Sigma_{33} \end{pmatrix}}_{\text{symmetric}} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix}$$

$$l=1 \quad a_1 = \varepsilon_{11} \beta_1 + \varepsilon_{12} \beta_2 + \varepsilon_{13} \beta_3$$

In general, can express

$$a_l = \sum_{k=1}^m \varepsilon_{kl} \beta_k$$

Sub in for β_k expression:

$$a_l = \sum_{k=1}^m \varepsilon_{kl} \left(\sum_{i=1}^n \frac{1}{\sigma_i^2} y_i f_k(x_i) \right)$$

indep. of y_i

$$\frac{\partial a_l}{\partial y_j} = \sum_{k=1}^m \varepsilon_{kl} \left(\sum_{i=1}^n \frac{1}{\sigma_i^2} \underbrace{\frac{\partial y_i}{\partial y_j} f_k(x_i)}_{\delta_{ij}} \right)$$

δ_{ij} "killer of sums"



$$\frac{f_k(x_j)}{\sigma_j^2}$$

$$\therefore \frac{\partial a_l}{\partial y_j} = \sum_{k=1}^m \varepsilon_{kl} \frac{f_k(x_j)}{\sigma_j^2}$$

To find the uncertainties in a_l , we will need to know $\left(\frac{\partial a_l}{\partial y_j}\right)^2$

Define $\sigma_{a_l a_{l'}}^2 = \sum_{j=1}^N \left[\sigma_j^2 \frac{\partial a_l}{\partial y_j} \frac{\partial a_{l'}}{\partial y_j} \right]$

With this definition, the uncertainty in a_l is found by setting $l' = l$.

$$\sigma_{a_l a_l}^2 = \sigma_{a_l}^2 = \sum_{j=1}^N \sigma_j^2 \left(\frac{\partial a_l}{\partial y_j} \right)^2$$

\uparrow
 $l' = l$

Start w/

$$\sigma_{a_l a_{l'}}^2 = \sum_{j=1}^N \left[\sigma_j^2 \left(\sum_{k=1}^m \epsilon_{k,l} \frac{f_k(x_j)}{\sigma_j^2} \right) \left(\sum_{p=1}^m \epsilon_{p,l'} \frac{f_p(x_j)}{\sigma_j^2} \right) \right]$$

$$\sigma_{\alpha_i \alpha_{i'}}^2 = \sum_{k=1}^m \left\{ \epsilon_{kl} \sum_{p=1}^m \left[\epsilon_{p'l} \sum_{j=1}^N \left(\frac{1}{f_j^2} f_k(x_j) f_p(x_j) \right) \right] \right\}$$

elements of the

$\underline{\underline{\alpha}}$ matrix $\underline{\underline{\alpha}}_{kp}$

$$\therefore \sigma_{\alpha_i \alpha_{i'}}^2 = \sum_{k=1}^m \left\{ \epsilon_{kl} \left(\sum_{p=1}^m \epsilon_{p'l} \alpha_{kp} \right) \right\} \quad \text{⊗}$$

Consider, for example, the 3×3 case of $\underline{\underline{\epsilon}} \underline{\underline{\alpha}}$

$$\begin{pmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{12} & \underline{\underline{\epsilon}}_{22} & \epsilon_{23} \\ \epsilon_{13} & \epsilon_{23} & \epsilon_{33} \end{pmatrix} \begin{pmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{12} & \alpha_{22} & \alpha_{23} \\ \alpha_{13} & \alpha_{23} & \alpha_{33} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$\underline{\underline{\epsilon}} = \underline{\underline{\alpha}}^{-1}$

$\underline{\underline{\alpha}} =$

$\underline{\underline{I}} =$ identity
matrix

$$1st \text{ Element : } \epsilon_{11} \alpha_{11} + \epsilon_{12} \alpha_{12} + \epsilon_{13} \alpha_{13} = 1 \quad \textcircled{a}$$

$$2nd \text{ Element : } \epsilon_{11} \alpha_{12} + \epsilon_{12} \alpha_{22} + \epsilon_{13} \alpha_{23} = 0 \quad \textcircled{b}$$

⋮

⋮

⋮

$m=3$

Compare to $\sum_{p=1}^m \epsilon_{pl'} \alpha_{kp}$

try $l'=k=1$: $\epsilon_{11} \alpha_{11} + \epsilon_{12} \alpha_{12} + \epsilon_{13} \alpha_{13} = 1$ by a

try $l'=1, k=2$: $\epsilon_{11} \alpha_{12} + \epsilon_{12} \alpha_{22} + \epsilon_{13} \alpha_{23} = 0$ by b

⋮ ⋮ ⋮

In general, $\sum_{p=1}^m \epsilon_{pl'} \alpha_{kp} = \delta_{l'k}$ ← Kronecker-delta → just the elements of the identity matrix \mathbb{I}

Sub this result into \otimes

$$\sigma_{\alpha_l \alpha_{l'}}^2 = \sum_{k=1}^m \epsilon_{kl} \underbrace{\delta_{l'k}}_{\text{"killer of sums"}} = \epsilon_{ll'}$$

"killer of sums"

$$\Rightarrow k = l'$$

$$\therefore \sigma_{\alpha_l \alpha_{l'}}^2 = \epsilon_{ll'}$$

The diagonal elements of ϵ give the squares of the uncertainties in the best-fit parameters.

To get the uncertainty in a_l parameter, set
 $l' = l$:

$$\sigma_{a_{ll}}^2 = \boxed{\sigma_{a_l}^2 = \Sigma_{ll}}$$

Eg. For 3 parameters (a_1, a_2, a_3)

$$\Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} & \Sigma_{13} \\ \Sigma_{12} & \Sigma_{22} & \Sigma_{23} \\ \Sigma_{13} & \Sigma_{23} & \Sigma_{33} \end{pmatrix}$$

called error
or covariance
matrix.

Σ_{11} is σ_1^2 ... square of uncertainty in a_1

Σ_{22} " σ_2^2 ... " " " " " a_2

Σ_{33} " σ_3^2 ... " " " " " a_3

The off-diagonal terms give the covariance

$$\sigma_{12} = \Sigma_{12} = \Sigma_{21} \text{ covariance between } a_1 \text{ and } a_2$$

Summary

Fits to funcs of the form:

$$y = a_1 f_1(x) + a_2 f_2(x) + \dots + a_m f_m(x)$$
$$= \sum_{k=1}^m a_k f_k(x)$$

Have measured $(x_i, y_i \pm \sigma_i)$ for $i=1..N$

$$\underline{a} = \underline{\Sigma} \underline{\beta}$$

$$\begin{matrix} \uparrow \\ \curvearrowright \end{matrix}$$

column matrix
of the best-fit
parameters.

$(x_i, y_i \pm \sigma_i)$ fully determine all of

$$\underline{\alpha}, \underline{\Sigma} = \underline{\alpha}^{-1}, \{ \underline{\beta} \}$$

There is no guess work involved when fitting

$$\text{data to a func of the form } y = \sum_{k=1}^m a_k f_k(x),$$

1. Calculate the elements of the β column matrix of the α square matrix.

$$\beta_l = \sum_{i=1}^N \frac{y_i}{\sigma_i^2} f_l(x_i) \quad l = 1..m$$

$$\alpha_{lk} = \sum_{i=1}^N \left[\frac{1}{\sigma_i^2} f_l(x_i) f_k(x_i) \right] \quad l = 1..m \quad k = 1..m$$

2. Invert α to find the error or covariance matrix:

$$\Sigma = \alpha^{-1} \quad (\text{software})$$

3. Calculate the best-fit parameters using

$$\underline{\alpha} = \underline{\Sigma} \underline{\beta}$$

4. The diagonal elements of Σ give the square of the uncertainties in the best-fit parameters.

$$f_{a_1} = \sqrt{\epsilon_{11}}$$

no additional
calculation
required!

$$f_{a_2} = \sqrt{\epsilon_{22}}$$

⋮
⋮

$$f_{a_m} = \sqrt{\epsilon_{mm}}$$