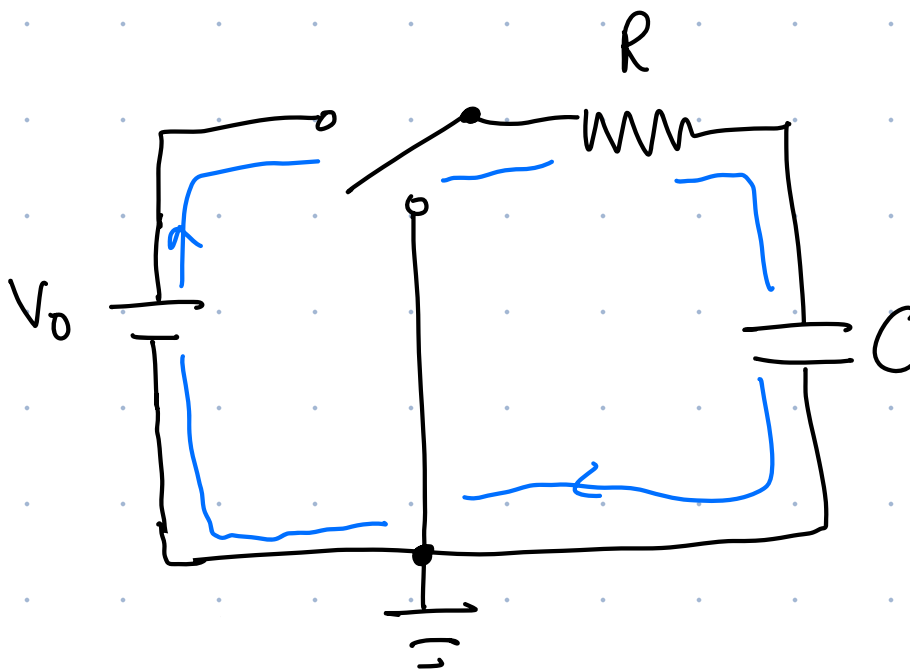


Previously: $|\Delta V_R| = IR = R \frac{dQ}{dt}$

$$|\Delta V_C| = \frac{1}{C} Q$$

Today: RC Circuit Transient Response.



Start w/
switch down
s.t. $Q=0$
 $I=0$

At $t=0$, flip switch up. Find $Q(t)$ as system approaches new equilibrium.

Kirchhoff Voltage loop rule.

$$V_0 - IR - \frac{Q}{C} = 0.$$

$$\therefore R \frac{dQ}{dt} + \frac{Q}{C} = V_0 \quad \text{divide by } R$$

$$\therefore \frac{dQ}{dt} + \frac{1}{RC} Q = \frac{V_0}{R} \quad \text{define } \tau = RC \quad \text{(time constant)}$$

$$\therefore \frac{dQ}{dt} + \frac{1}{\tau} Q = \frac{V_0}{R} \quad (*)$$

inhomogeneous first order differential eq'n.

Goal: Solve for $Q(t)$ subject to initial condition

$$\rightarrow Q(0) = 0.$$

After switch has been up for a long time, capacitor is fully charged s.t. Q is const.

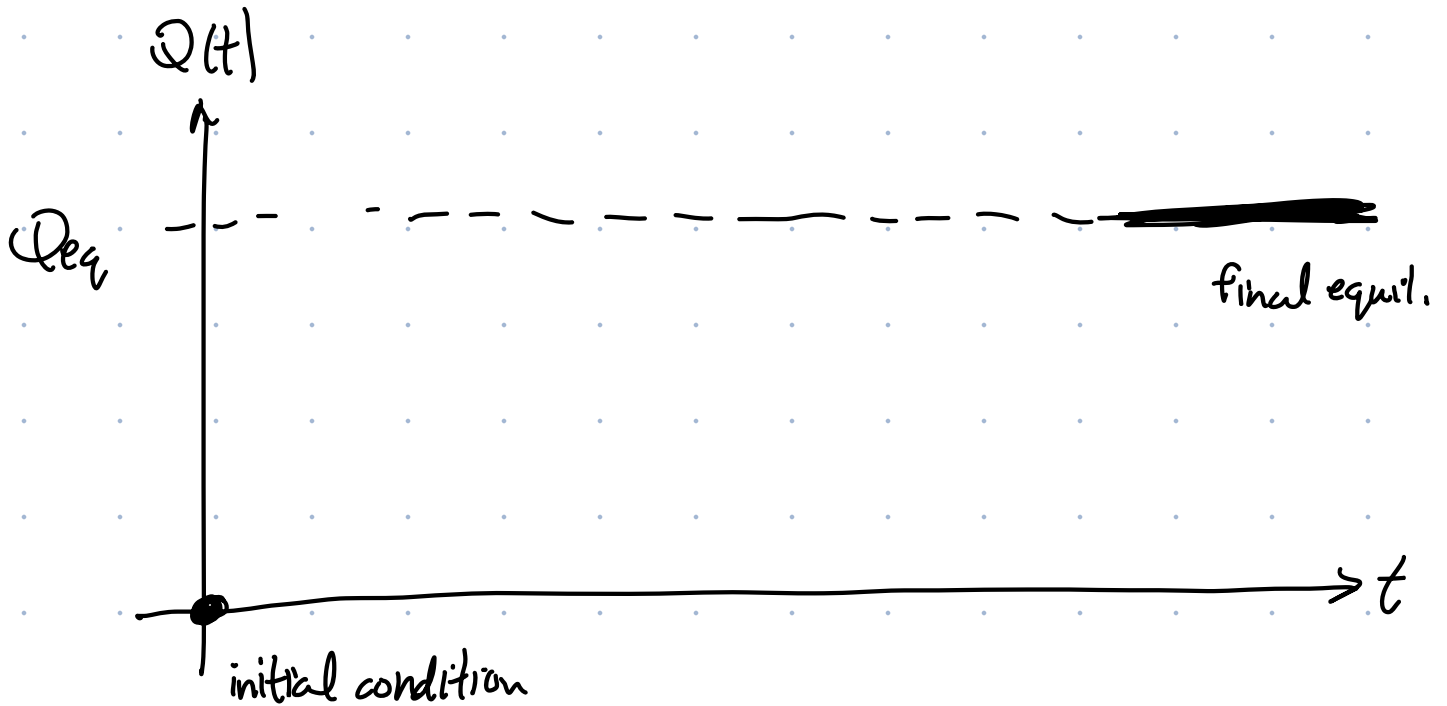
$$\text{and } \frac{dQ}{dt} = 0.$$

$$t \rightarrow \infty, \text{ expect } \frac{dQ}{dt} \rightarrow 0 \quad Q \rightarrow Q_{eq}$$

sub into ④

$$0 + \frac{1}{\tau} Q_{eq} = \frac{V_0}{R}$$

$$\therefore Q_{eq} = \tau \frac{V_0}{R} = \cancel{RC} \frac{V_0}{\cancel{R}} = CV_0.$$



Express $Q(t) = Q_h(t) + \frac{Q_{eq}}{CV_0} \text{ (const.)}$.

Sub into ④

$$\begin{aligned} \textcircled{4} \text{ Requires } \frac{dQ}{dt} &= \frac{d}{dt} (Q_h(t) + CV_0) \\ &= \frac{dQ_h(t)}{dt} \end{aligned}$$

$\therefore$ ④ becomes:

$$\frac{dQ_h(t)}{dt} + \frac{1}{\tau} (Q_h(t) + CV_0) = \frac{V_0}{R}$$

$$\therefore \frac{dQ_h(t)}{dt} + \frac{1}{\tau} Q_h(t) + \underbrace{\frac{1}{\tau} CV_0}_{\frac{1}{RC} CV_0 = \frac{V_0}{R}} = \cancel{\frac{V_0}{R}} \quad \textcircled{0}$$

$$\therefore \frac{dQ_h(t)}{dt} + \frac{1}{\tau} Q_h(t) = 0 \quad \textcircled{\#}$$

homogenous first order differential Eq'n
(easier to solve).

multiply ⑧ by dt

$$dQ_h(t) + Q_h(t) \frac{dt}{\tau} = 0 \quad \text{move 2nd term to right.}$$

$$dQ_h(t) = -Q_h(t) \frac{dt}{\tau} \quad \text{divide by } Q_h(t)$$

$$\frac{dQ_h(t)}{Q_h(t)} = -\frac{dt}{\tau} \quad \text{integrate.}$$

$$\int \frac{dQ_h(t)}{Q_h(t)} = -\frac{1}{\tau} \int dt$$

integration const.

$$\therefore \ln Q_h(t) = -\frac{1}{\tau} t + B$$

$$\therefore Q_h(t) = e^{-t/\tau + B} = e^{-t/\tau} \underbrace{e^B}_{\equiv B'} \text{ just another const.}$$

$$\therefore Q_h(t) = B' e^{-t/\tau}$$

To get the final $Q(t) = \underbrace{Q_h(t)}_{B' e^{-t/\tau}} + \underbrace{Q_{eq}}_{CV_0}$

$$\therefore Q(t) = B' e^{-t/\tau} + CV_0.$$

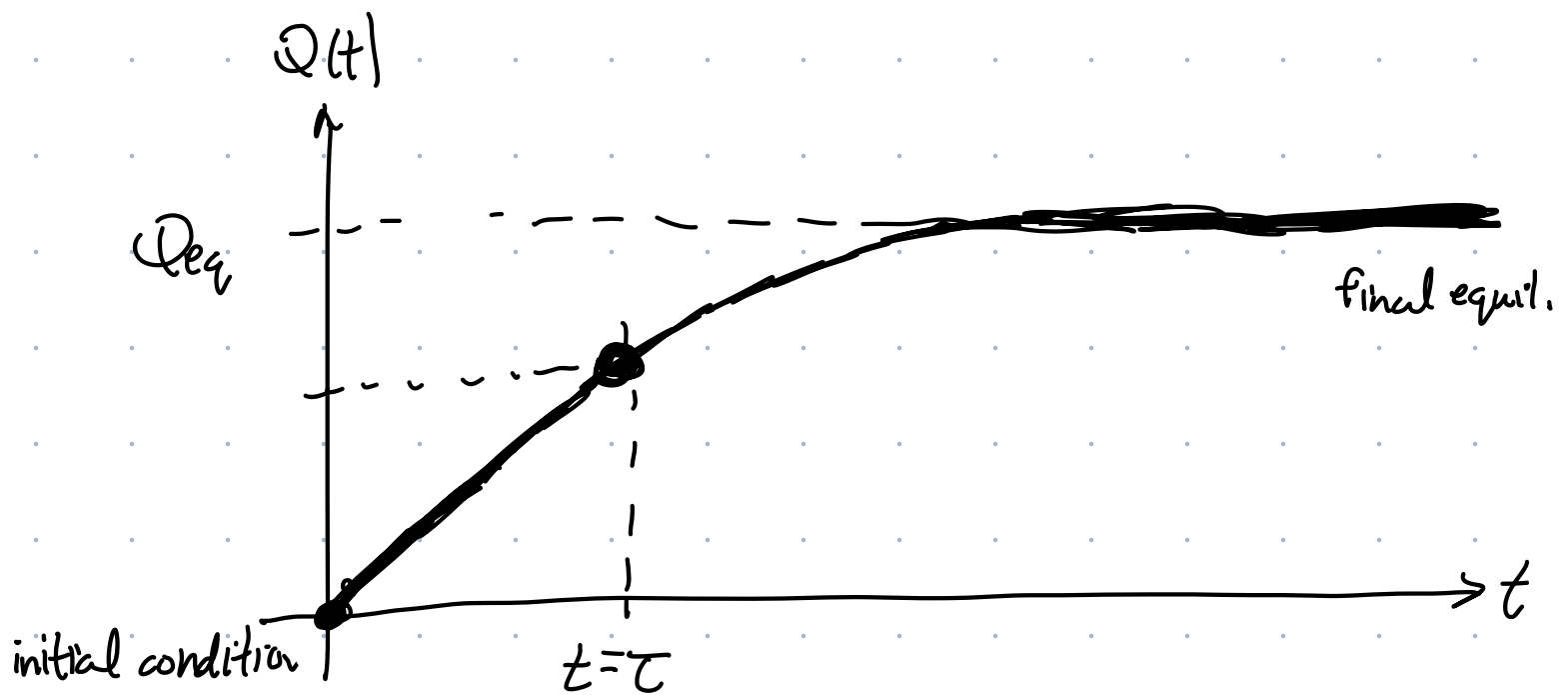
Last step is to use the initial condition $Q(0) = 0$ to determine B' .

$$\underbrace{Q(0)}_0 = B' \cancel{e^0}^1 + CV_0 \quad \therefore \underline{B' = -CV_0}$$

Finally $Q(t) = CV_0 \left[1 - e^{-t/\tau} \right]$

where $\tau = RC$

Transient response of cap. charging
from $Q(0) = 0$ to Q_{eq} .



Consider where $t = \tau$

$$Q(\tau) = CV_0 \left[1 - e^{-\tau/\tau} \right]$$

$$= CV_0 \left(1 - \frac{1}{e} \right)$$

0.632

When charging a cap through a resistor, it takes $\sim 4-5$ time constants $\tau = RC$ to get close to fully charged.

We will investigate RC circuit transients in Lab #3.

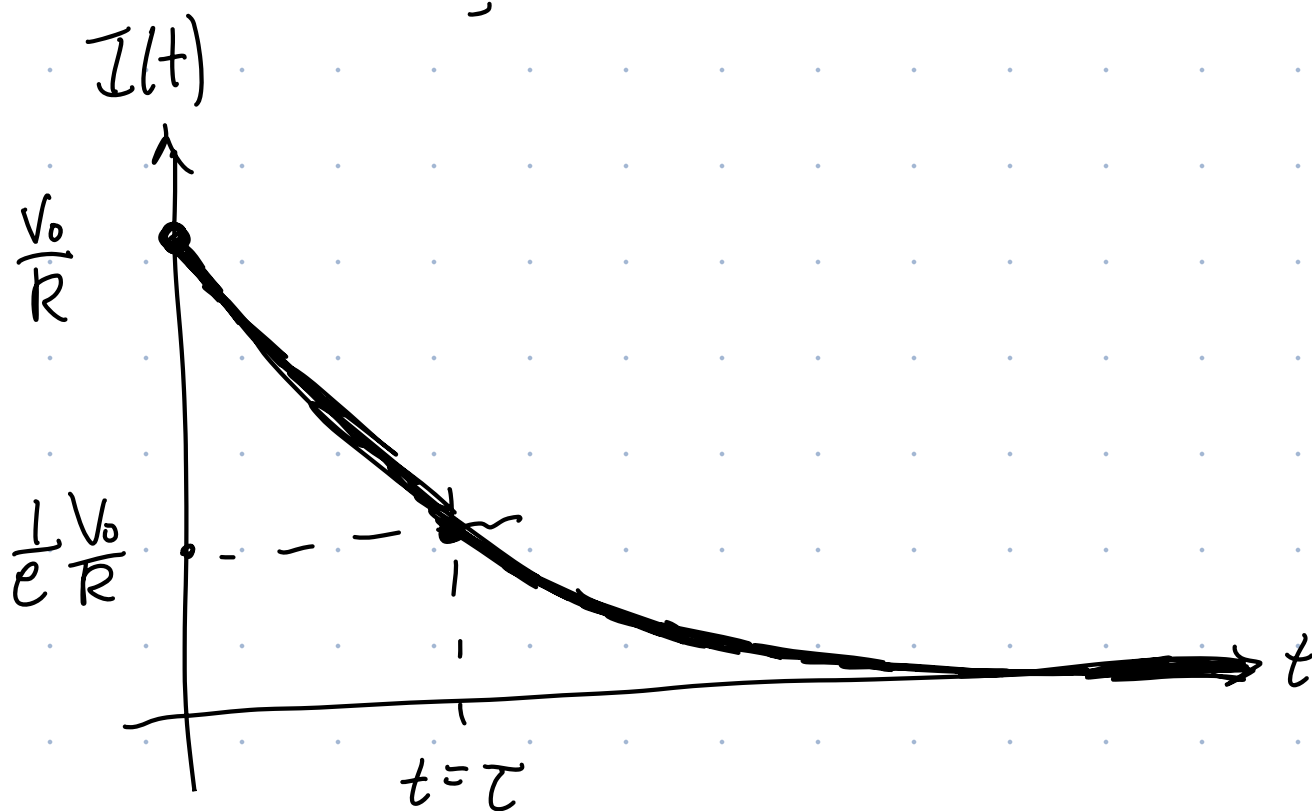
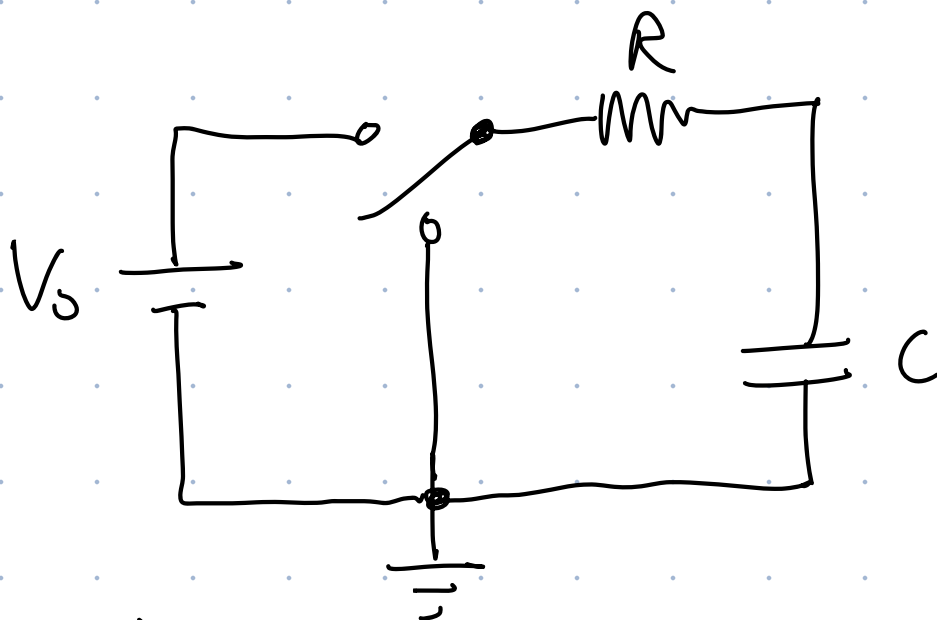
Having found $Q(t)$, we can find the current $I(t) = \frac{dQ}{dt}$

$$I(t) = \frac{d}{dt} \left\{ CV_0 [1 - e^{-t/\tau}] \right\}$$

$$= CV_0 \frac{d}{dt} [1 - e^{-t/\tau}]$$

$$= \frac{CV_0}{\tau} e^{-t/\tau} = \frac{\cancel{C}V_0}{\cancel{RC}} e^{-t/\tau}$$

$$\therefore I(t) = \frac{V_0}{R} e^{-t/\tau}$$



Consider $t = \tau$:
$$I(\tau) = \frac{V_0}{R} e^{-\tau/\tau} = \frac{1}{e} \frac{V_0}{R}$$

Uncertainties & Propagation of Errors.

Every quantity that is measured has an associated uncertainty.

Recall first-year prop. of error rules:

$$\text{Meas. } x \pm \Delta x, \quad y \pm \Delta y$$

$$(1) \quad z = x \pm y \Rightarrow \Delta z = \Delta x + \Delta y$$

$$(2) \quad z = xy \quad \text{or} \quad z = \frac{x}{y} \Rightarrow \frac{\Delta z}{z} = \frac{\Delta x}{x} + \frac{\Delta y}{y}$$

$$(3) \quad z = x^n \Rightarrow \frac{\Delta z}{z} = n \frac{\Delta x}{x}$$

One of our goals will be to discover the origin of these rules and then generalize to cover all cases, including things like

$$z = e^x, \quad z = \ln x, \quad z = \sin x \dots$$