

Last Time: Propagation of Errors

$$\text{If } y = f(x_1, x_2, \dots, x_N)$$

$$\begin{aligned} \text{meas } & x_1 \pm \Delta x_1 \\ & x_2 \pm \Delta x_2 \end{aligned}$$

$$\vdots$$

$$x_N \pm \Delta x_N$$

then

$$\Delta y = \sqrt{\left(\frac{\partial y}{\partial x_1} \Delta x_1\right)^2 + \left(\frac{\partial y}{\partial x_2} \Delta x_2\right)^2 + \dots + \left(\frac{\partial y}{\partial x_N} \Delta x_N\right)^2}$$

Today: Examples of prop. of error.

$$\textcircled{1} \quad R = \frac{V}{I} \quad \text{meas. } \begin{array}{l} V \pm \Delta V \\ I \pm \Delta I \end{array} \Rightarrow \text{find } \Delta R.$$

First-year $\frac{\Delta R}{R} = \frac{\Delta V}{V} + \frac{\Delta I}{I}$

From prop. of errors: $\Delta R = \sqrt{\left(\frac{\partial R}{\partial V} \Delta V\right)^2 + \left(\frac{\partial R}{\partial I} \Delta I\right)^2}$

$$\frac{\partial R}{\partial V} = \frac{\partial}{\partial V} \left(\frac{V}{I} \right) = \frac{1}{I}$$

$$\frac{\partial R}{\partial I} = \frac{\partial}{\partial I} \left(\frac{V}{I} \right) = -\frac{V}{I^2}$$

$$\therefore \Delta R = \sqrt{\left(\frac{1}{I} \Delta V\right)^2 + \left(\frac{V}{I^2} \Delta I\right)^2}$$

To compare to first-year rule, find $\frac{\Delta R}{R}$

$$\frac{\Delta R}{R} = \frac{1}{R} \sqrt{\left(\frac{V}{I} \frac{\Delta V}{V}\right)^2 + \left(\frac{V}{I} \frac{\Delta I}{I}\right)^2}$$

$$= \cancel{\frac{1}{R}} \sqrt{\cancel{R^2} \left(\frac{\Delta V}{V}\right)^2 + \cancel{R^2} \left(\frac{\Delta I}{I}\right)^2}$$

$$\therefore \frac{\Delta R}{R} = \sqrt{\left(\frac{\Delta V}{V}\right)^2 + \left(\frac{\Delta I}{I}\right)^2}$$

Like the first-year rule
w/ a quadrature sum.

Example $y = Ax^n$ Powers. Assume
 \uparrow const meas. $x \pm \Delta x$ A, n const.
w/ $\Delta A = \Delta n = 0$

First year $\frac{\Delta y}{y} = \left| n \frac{\Delta x}{x} \right|$

Prop. of errors

$$\Delta y = \sqrt{\left(\frac{\partial y}{\partial x} \Delta x \right)^2}$$

$$\frac{\partial y}{\partial x} = \frac{\partial}{\partial x} (Ax^n) = Anx^{n-1}$$

$$\Delta y = \sqrt{(Anx^{n-1} \Delta x)^2} = |Anx^{n-1} \Delta x|$$

Consider $\frac{\Delta y}{y} = \frac{|Anx^{n-1} \Delta x|}{|Ax^n|} = \left| n \frac{\Delta x}{x} \right|$

\uparrow first-year result.

Another example. $y = x \ln x$ meas. $x \pm \Delta x$
find Δy .

No first-year rule, but prop. of errors still works!

$$\Delta y = \sqrt{\left(\frac{\partial y}{\partial x} \Delta x\right)^2} = \left| \frac{\partial y}{\partial x} \Delta x \right|$$

$$\frac{dy}{dx} = \frac{d}{dx}(x \ln x) = \ln x + x \left(\frac{1}{x}\right)$$

$$\frac{dy}{dx} = \ln x + 1$$

$$\therefore \Delta y = |(\ln x + 1) \Delta x|$$

Try to justify/derive the standard error in the mean.

$$\sigma_{\mu} = \frac{\sigma}{\sqrt{N}}$$

std. error. \leftarrow std. dev. \leftarrow no. of trials

Strategy is to write down an expression for the mean μ & then apply prop. of errors.

$$\mu = \frac{1}{N} (x_1 + x_2 + x_3 + \dots + x_N)$$

meas. $x_1 \pm \Delta x_1$
 $x_2 \pm \Delta x_2$
 \vdots
 $x_N \pm \Delta x_N$

fun of N variables.

Prop. of errors says:

$$\Delta \mu = \sqrt{\left(\frac{\partial \mu}{\partial x_1} \Delta x_1\right)^2 + \left(\frac{\partial \mu}{\partial x_2} \Delta x_2\right)^2 + \dots + \left(\frac{\partial \mu}{\partial x_N} \Delta x_N\right)^2}$$

$$\frac{\partial \mu}{\partial x_1} = \frac{\partial}{\partial x_1} \left[\frac{1}{N} (x_1 + x_2 + \dots + x_N) \right]$$

$$= \frac{1}{N} \left[\frac{\partial x_1}{\partial x_1} + \frac{\partial x_2}{\partial x_1} + \dots + \frac{\partial x_N}{\partial x_1} \right]$$

(Note: Red arrows point from $\frac{\partial x_2}{\partial x_1}$ and $\frac{\partial x_N}{\partial x_1}$ to 0, and a red wavy line is under $\frac{\partial x_1}{\partial x_1}$)

$$= \frac{1}{N}$$

(Note: A red '1' is written under the fraction)

Likewise, $\frac{\partial \mu}{\partial x_2} = \frac{1}{N}$, $\frac{\partial \mu}{\partial x_3} = \frac{1}{N}$..., $\frac{\partial \mu}{\partial x_N} = \frac{1}{N}$

$$\begin{aligned}\therefore \Delta \mu &= \sqrt{\left(\frac{1}{N} \Delta x_1\right)^2 + \left(\frac{1}{N} \Delta x_2\right)^2 + \dots + \left(\frac{1}{N} \Delta x_N\right)^2} \\ &= \frac{1}{N} \sqrt{(\Delta x_1)^2 + (\Delta x_2)^2 + \dots + (\Delta x_N)^2}\end{aligned}$$

Typically each individual meas. is expected to be approx $\pm \sigma$ from μ (on average).

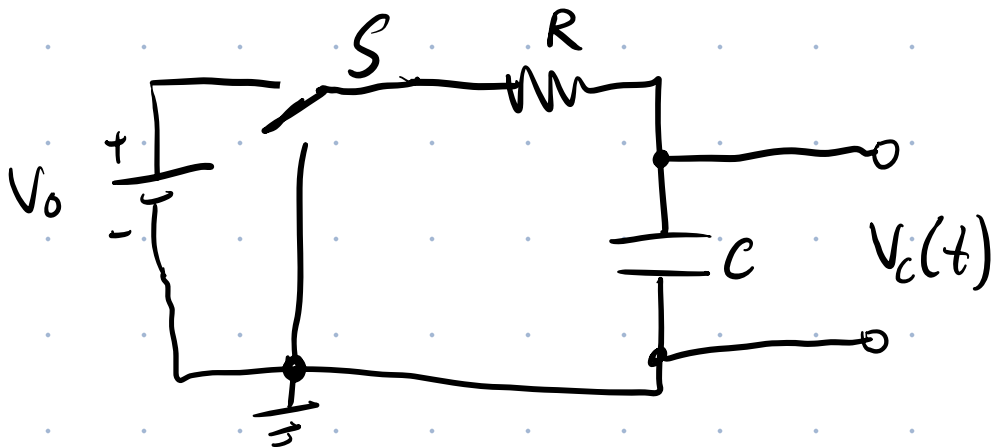
$$\therefore \Delta x_1 \approx \Delta x_2 \approx \dots \approx \Delta x_N \approx \sigma \text{ (std. dev.)}$$

$$\Delta \mu = \frac{1}{N} \sqrt{\sigma^2 + \sigma^2 + \dots + \sigma^2} = \frac{1}{N} \sqrt{N \sigma^2} = \frac{\sigma}{\sqrt{N}}$$

$$\boxed{\therefore \Delta \mu = \frac{\sigma}{\sqrt{N}}} \text{ as expected!}$$

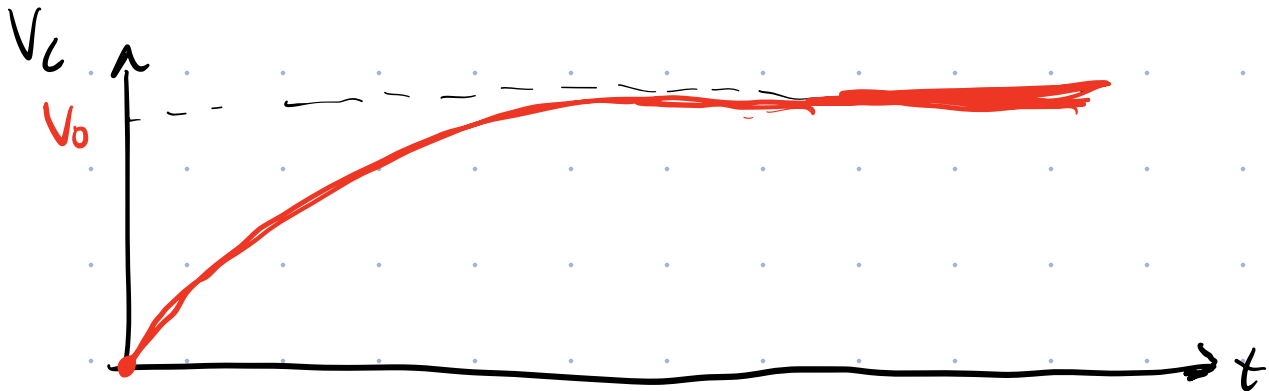
Lab #3 Preview

Charge a cap. through a resistor



If close switch at $t=0$,

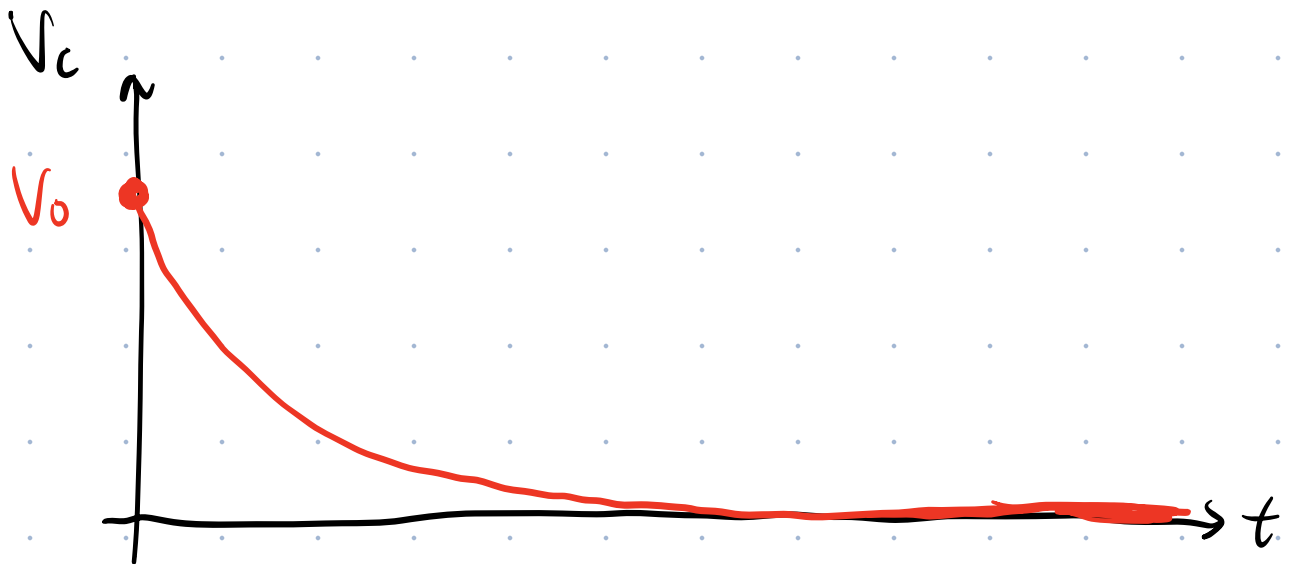
$$V_c(t) = V_0 (1 - e^{-t/\tau}) \quad \tau = RC$$



Discharging a cap. through resistor R

Cap. initially charged to V_0 . Flip switch down @ $t=0$.

$$V_c(t) = V_0 e^{-t/\tau} \quad \tau = RC$$



In Lab, we will use square wave to simulate a switch.

