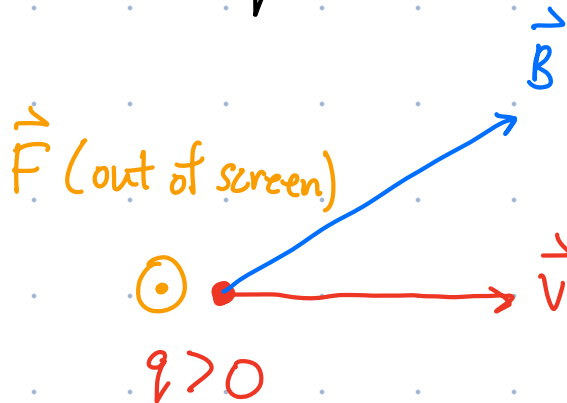


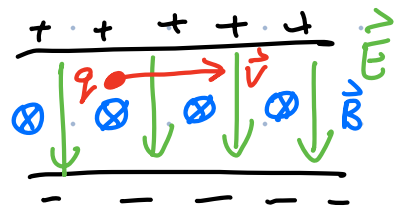
- Next Prairie Learn HW due Mar. 28
- Complete Pre-Lab #8 before the start of your lab.
- Office hours: 12:00-13:00 Tuesday (instead of 14:30-15:30 today).

Last Time: Force on a charge moving through a magnetic field.

$$\vec{F} = q \vec{v} \times \vec{B}$$



Velocity selector



q undeflected

$$\text{when } F_E = F_B \Rightarrow qE = qvB \Rightarrow v = \frac{E}{B}$$

Today!

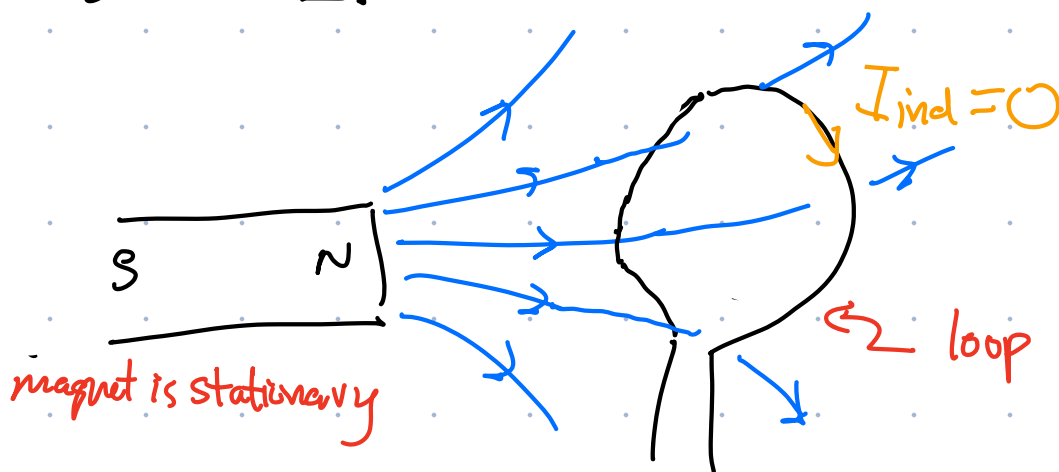
Start by discussing/motivating Lab #8

currents

- changing dist'n of charge creates magnetic fields
- today, we will see that changing magnetic fields can create currents $\Rightarrow$ Faraday's Effect.

When a magnetic field passing through a loop of wire changes, get an induced current I_{ind} in the loop.

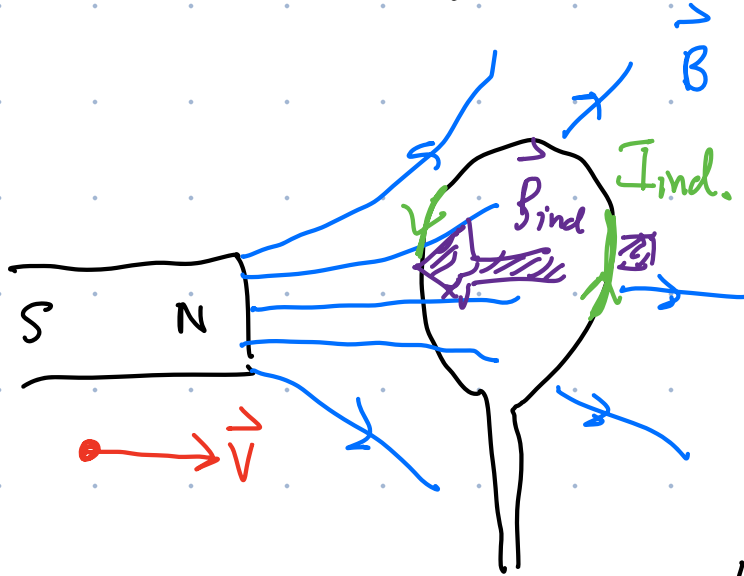
Scenario 1.



In scenario 1, with loop & magnet stationary, get no current in loop.

loop is stationary.

Scenario 2: Magnet moves towards the loop.

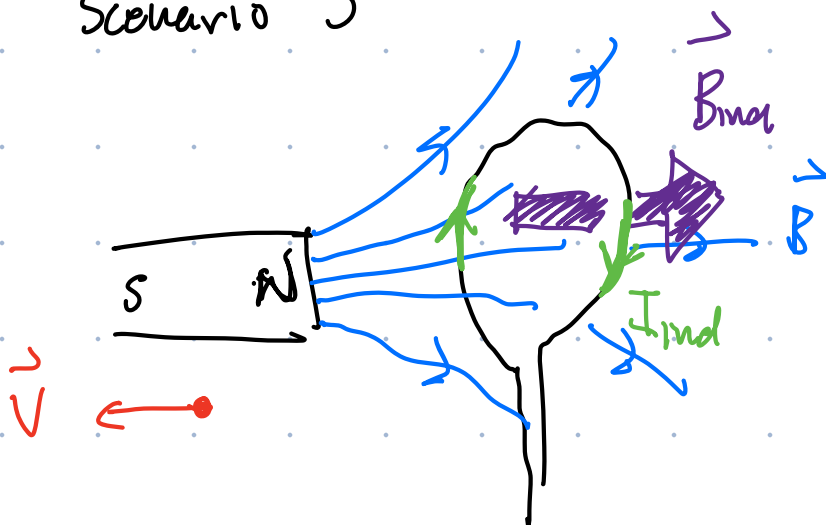


In this case, from the perspective of an observer on the magnet, charges in the loop of wire are moving towards the bar magnet & through its magnetic field $\vec{B}$.

As a result, these charges experience a force & their motion gives rise to an induced current, I_{ind} .

I_{ind} creates $\vec{B}_{ind}$ that opposes the increase in $\vec{B}$ through the loop. $\rightarrow$ Faraday's Law.

Scenario 3

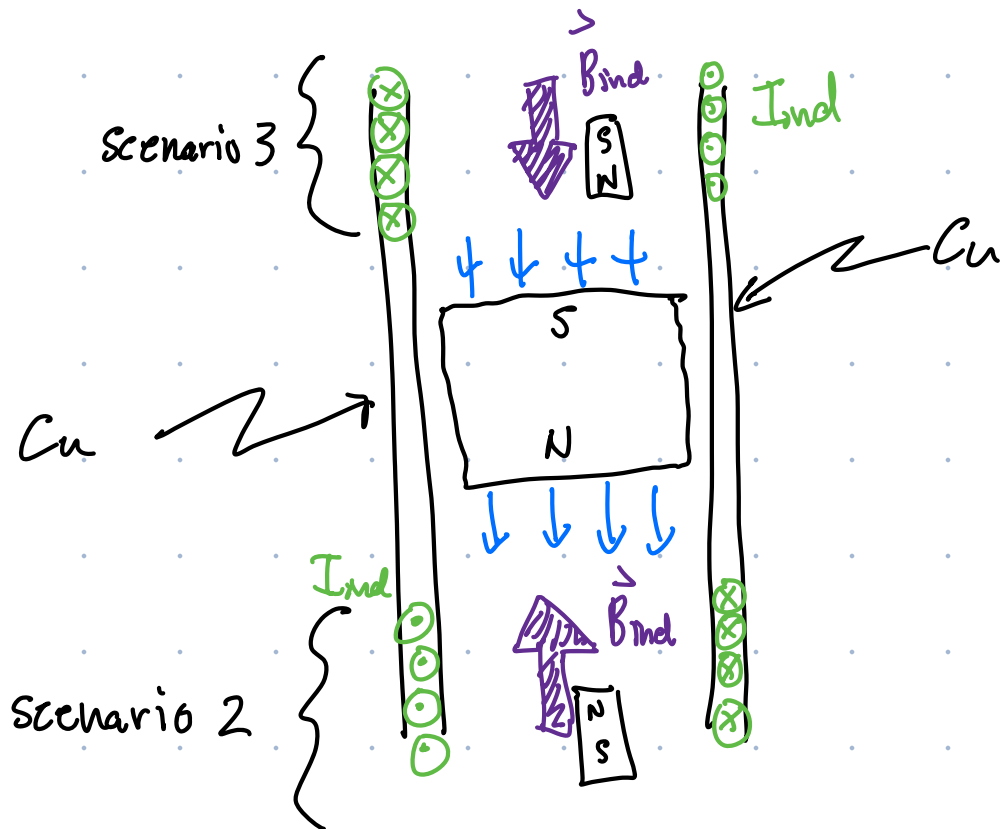


In this case, I_{ind} creates a $\vec{B}_{ind}$ to oppose the decreasing magnetic field through the loop.

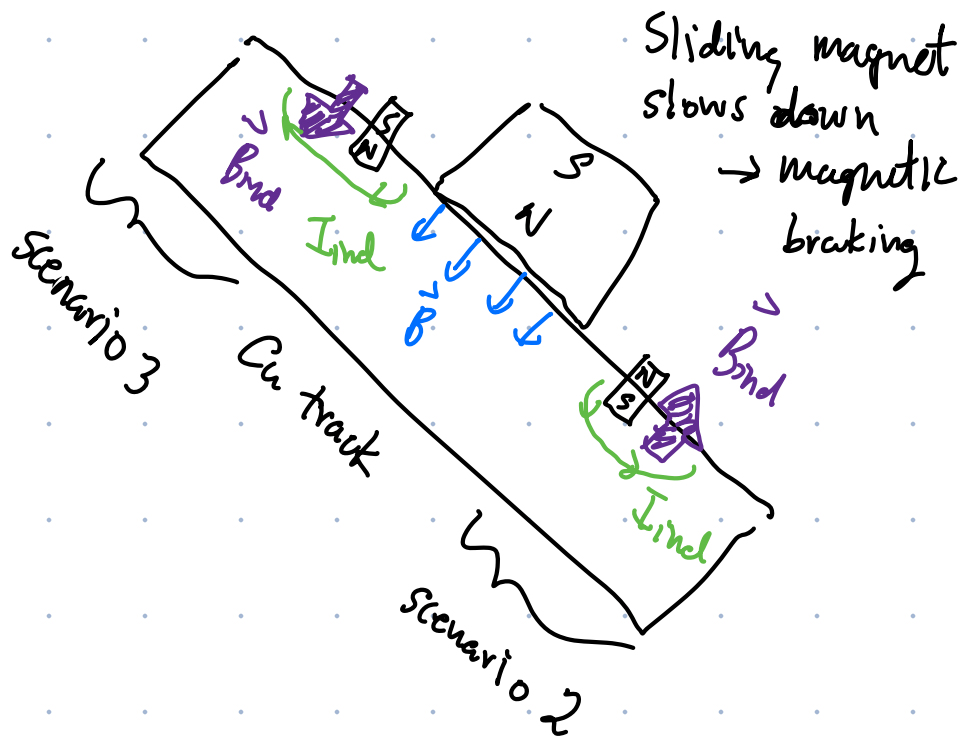
$$\vec{F} = q\vec{v} \times \vec{B}$$

For a magnet falling through a copper tube...

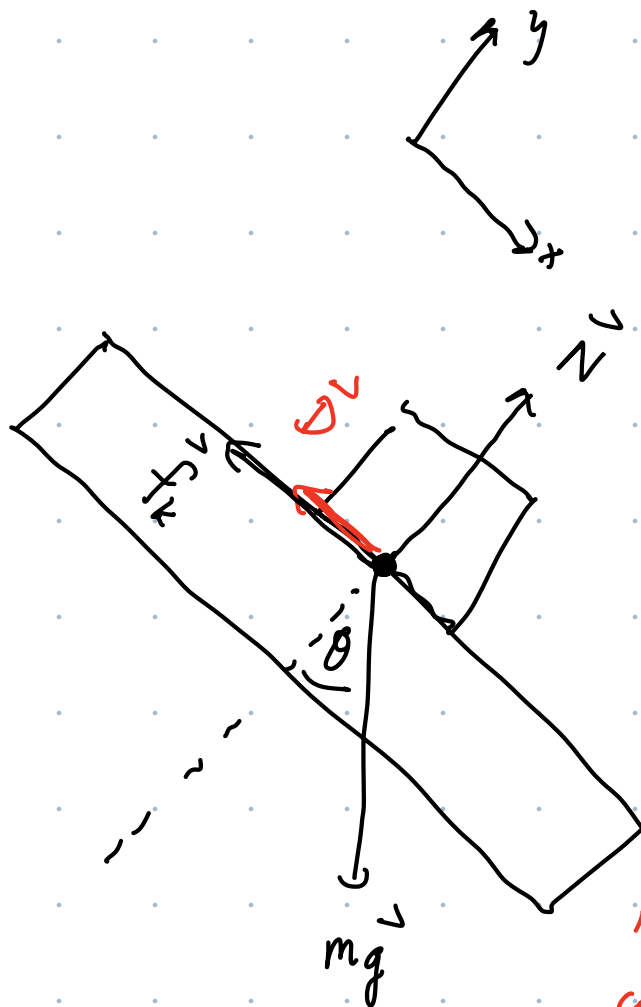
cross-section



Lab # 8



FBD



$\vec{D}$: drag force due to the magnetic interaction w/ induced currents.

Model the drag force as

$$D = b v$$

"drag coefficient" speed of magnet

y-dir'n:

$$m a_y = 0 = N - m g \cos \theta$$

$$\Rightarrow N = \underline{m g \cos \theta}$$

x-dir'n

$$m a_x = m g \sin \theta - \underbrace{\mu_k N}_{f_k} - \underbrace{b v}_D$$

$$\therefore m a_x = m g \sin \theta - \mu_k m g \cos \theta - b v$$

divide by m

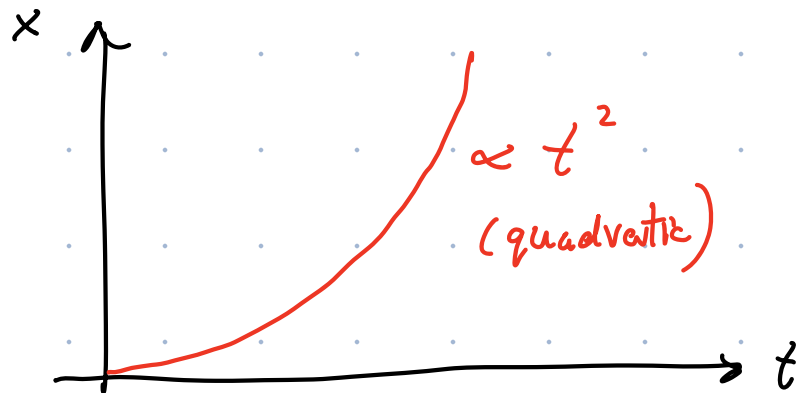
$$a_x = g (\sin \theta - \mu_k \cos \theta) - \frac{b}{m} v$$

acceleration of the magnet.

Case ①: If track is not conducting $\Rightarrow b = 0$

$$a_x = g (\sin \theta - \mu_k \cos \theta) = \text{const.}$$

Since a_x is const, $x = \frac{1}{2} a_x g t^2$

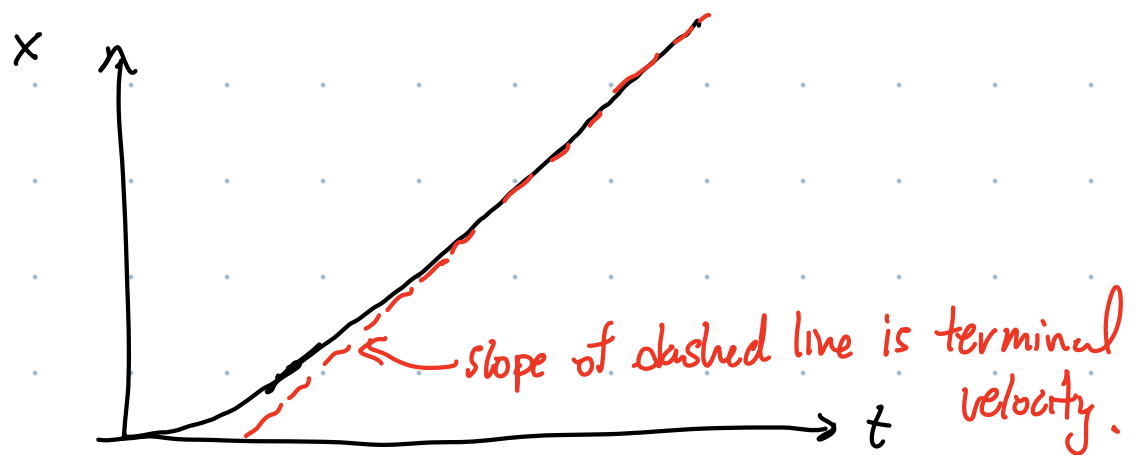


Case ② $b \neq 0$ (cu track)

$$a_x = g (\sin \theta - \mu_k \cos \theta) - \frac{b}{m} v$$

In this case, as magnet speeds up, the acceleration decreases. Eventually, reach a "terminal" velocity for which $a_x = 0$ and magnet slides at a const. speed.

(i) b is small, approach to terminal velocity is slow.



(ii) b is large, reach terminal velocity quickly

